

Parallel RTC With CPU Supervisor

Features

- Real-Time Clock counts seconds through years in BCD format
- On-chip battery-backup switchover circuit with nonvolatile control for external SRAM
- ► Less than 500nA of clock operation current in backup mode
- Microprocessor reset valid to V_{CC} = V_{SS}
- Independent watchdog timer with a programmable time-out period
- Power-fail interrupt warning
- Programmable clock alarm interrupt active in battery-backup mode
- ► Programmable periodic interrupt
- ► Battery-low warning

General Description

The bq4845 Real-Time Clock is a low-power microprocessor peripheral that integrates a time-of-day clock, a 100-year calendar, and a CPU supervisor in a 28-pin SOIC or DIP. The bq4845 is ideal for fax machines, copiers, industrial control systems, point-of-sale terminals, data loggers, and computers.

The bq4845 provides direct connections for a 32.768KHz quartz crystal and a 3V backup battery. Through the use of the conditional chip enable output (\overline{CE}_{OUT}) and battery voltage output (V_{OUT}) pins, the bq4845 can write-protect and make nonvolatile external SRAMs. The backup cell powers the real-time clock and maintains SRAM information in the absence of system voltage.

The bq4845 contains a temperaturecompensated reference and comparator circuit that monitors the status of its voltage supply. When the bq4845 detects an out-of-tolerance condition, it generates an interrupt warning and subsequently a microprocessor reset. The reset stays active for 200ms after V_{CC} rises within tolerance, to allow for power supply and processor stabilization.

The bq4845 also has a built-in watchdog timer to monitor processor operation. If the microprocessor does not toggle the watchdog input (WDI) within the programmed time-out period, the bq4845 asserts WDO and RST. WDI unconnected disables the watchdog timer.

The bq4845 can generate other interrupts based on a clock alarm condition or a periodic setting. The alarm interrupt can be set to occur from once per second to once per month. The alarm can be made active in the battery-backup mode to serve as a system wake-up call. For interrupts at a rate beyond once per second, the periodic interrupt can be programmed with periods of 30.5µs to 500ms.

Pin Connections

| Vоит 🗆 | | 28 | |
|-------------------|-------------|------|-------------------|
| Х1 С | 2 | 27 | |
| X ₂ | 3 | 26 | |
| WDO C | 4 | 25 | |
| INT C | 5 | 24 | 占 вс |
| RST [| 6 | 23 | b wdi |
| A3 🗆 | 7 | 22 | |
| A ₂ [| 8 | 21 | |
| A1 🗆 | 9 | 20 | ⊐ v _{ss} |
| A ₀ [| 10 | 19 | |
| DQ0 [| 11 | 18 | |
| DQ1 [| 12 | 17 | DQ5 |
| DQ ₂ | 13 | 16 | DQ4 |
| V _{SS} 🗆 | 14 | 15 | DQ3 |
| L | | | 1 |
| | 28-DIP or S | SOIC | |
| | | | PN484501.eps |

Pin Names

| A0-A3 | Clock/control address inputs | BC | Backup battery input |
|----------------------------------|------------------------------|------------------|------------------------|
| DO ₀ –DO ₇ | Data inputs/outputs | V _{OUT} | Back-up battery output |
| WE | Write enable | ĪNT | Interrupt output |
| ŌĒ | Output enable | RST | Microprocessor reset |
| \overline{CS} | Chip select input | WDI | Watchdog input |
| \overline{CE}_{IN} | External RAM chip enable | WDO | Watchdog output |
| CEOUT | Conditional RAM chip | V _{CC} | +5V supply |
| | enable | V _{SS} | Ground |
| X1-X2 | Crystal inputs | | |

Functional Description

Figure 1 is a block diagram of the bq4845. The following sections describe the bq4845 functional operation including clock interface, data-retention modes, power-on reset timing, watchdog timer activation, and interrupt generation.

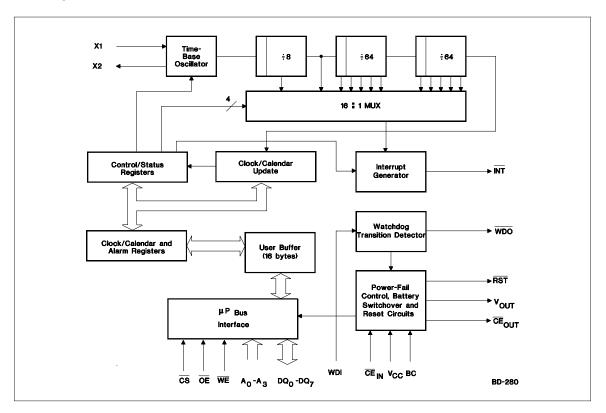


Figure 1. Block Diagram

Truth Table

| V _{cc} | CS | ŌĒ | WE | CEOUT | V _{OUT} | Mode | DQ | Power |
|-------------------------------|-------------------|-----|-------------------|----------------------|-------------------|----------|------------------|---------------------|
| < V _{CC} (max.) | V_{IH} | Х | Х | \overline{CE}_{IN} | V _{OUT1} | Deselect | High Z | Standby |
| | V _{IL} | Х | VIL | \overline{CE}_{IN} | V _{OUT1} | Write | D _{IN} | Active |
| > V _{CC} (min.) | V _{IL} | VIL | V_{IH} | \overline{CE}_{IN} | V _{OUT1} | Read | D _{OUT} | Active |
| | VIL | VIH | VIH | \overline{CE}_{IN} | V _{OUT1} | Read | High Z | Active |
| $< V_{PFD}$ (min.) $> V_{SO}$ | Х | Х | Х | Voh | Vout1 | Deselect | High Z | CMOS standby |
| $\leq V_{SO}$ | Х | Х | Х | VOHB | Vout2 | Deselect | High Z | Battery-backup mode |

Pin Descriptions

X1-X2 Crystal inputs

X1–X2 are a direct connection for a 32.768kHZ, 6pF crystal.

RST Reset output

 $\label{eq:RST} \begin{array}{l} \hline RST & goes & low & whenever & V_{CC} & falls & below & the \\ power & fail & threshold. \hline RST & will & remain & low & for \\ 200ms & typical & after & V_{CC} & crosses & the & threshold \\ on & power-up. & RST & also & goes & low & whenever & a \\ watchdog & timeout & occurs. & \hline RST & is & an & open- \\ drain & output. & \end{array}$

INT Interrupt output

INT goes low when a power fail, periodic, or alarm condition occurs. INT is an open-drain output.

WDI Watchdog input

WDI is a three-level input. If WDI remains either high or low for longer than the watchdog time-out period (1.5 seconds default), WDO goes low. WDO remains low until the next transition at WDI. Leaving WDI unconnected disables the watchdog function. WDI connects to an internal voltage divider between V_{OUT} and V_{SS}, which sets it to mid-supply when left unconnected.

WDO Watchdog output

WDO goes low if WDI remains either high or low longer than the watchdog time-out period. WDO returns high on the next transition at WDI. WDO remains high if WDI is unconnected.

A₀-A₃ Clock address inputs

 A_0-A_3 allow access to the 16 bytes of realtime clock and control registers. Vcc

DQ₀-DQ₇ Data input and output

 DQ_0-DQ_7 provide x8 data for real-time clock information. These pins connect to the memory data bus.

Ground

Vss

CS Chip select

OE Output enable

OE provides the read control for the RTC memory locations.

CEOUT Chip enable output

 \overline{CE}_{OUT} goes low only when \overline{CE}_{IN} is low and V_{CC} is above the power fail threshold. If \overline{CE}_{IN} is low, and power fail occurs, \overline{CE}_{OUT} stays low for 100 μ s or until \overline{CE}_{IN} goes high, whichever occurs first.

CEIN Chip enable input

 $\overline{\mbox{CE}_{\mbox{IN}}}$ is the input to the chip-enable gating circuit.

BC Backup battery input

BC should be connected to a 3V backup cell. A voltage within the V_{BC} range on the BC pin should be present upon power up to provide proper oscillator start-up.

Vout Output supply voltage

 V_{OUT} provides the higher of V_{CC} or $V_{BC}, \ switched \ internally, to supply external RAM.$

WE Write enable

WE provides the write control for the RTC memory locations.

Input supply voltage

+5V input

Address Map

The bq4845 provides 16 bytes of clock and control status registers. Table 1 is a map of the bq4845 registers, and Table 2 describes the register bits.

Clock Memory Interface

The bq4845 has the same interface for clock/calendar and control information as standard SRAM. To read and write to these locations, the user must put the bq4845 in the proper mode and meet the timing requirements.

Read Mode

The bq4845 is in read mode whenever \overline{OE} (Output enable) is low and \overline{CS} (chip select) is low. The unique address, specified by the 4 address inputs, defines which one of the 16 clock/calendar bytes is to be accessed. The bq4845 makes valid data available at the data I/O pins within t_{AA} (address access time). This occurs after the last address input signal is stable, and providing the \overline{CS} and \overline{OE} (output enable) access times are met. If the \overline{CS} and \overline{OE} access times are not met, valid data is available after the latter of chip select access time (t_{ACS}) or output enable access time (t_{OE}).

 \overline{CS} and \overline{OE} control the state of the eight three-state data I/O signals. If the outputs are activated before $t_{AA},$

| Ad- dress (h) | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | 12-Hour Range (h) | Register |
|---------------------|---------------|--------------|---------------|----------|--------------|---------|------------|------|----------------------|------------------------|
| 0 | 0 | 10-s | econd d | igit | | 1-secon | ıd digit | | 00–59 | Seconds |
| 1 | ALM1 | ALM0 10-s | econd d | igit | | 1-secon | ıd digit | | 00–59 | Seconds alarm |
| 2 | 0 | 10-n | ninute d | igit | | 1-minu | te digit | | 00-59 | Minutes |
| 3 | ALM1 | ALM0 | ninute d | iơit | | 1-minu | te digit | | 00–59 | Minutes alarm |
| 4 | PM/AM | 0 | | ır digit | | 1-hou | r digit | | 01–12 AM/ 81– 92 PM | Hours |
| 5 | ALM1 PM/AM | ALM0 | 10-hour digit | | 1-hour digit | | | | 01–12 AM/ 81–92 PM | Hours alarm |
| 6 | 0 | 0 | 10-da | y digit | | 1-day | digit | | 01-31 | Day |
| 7 | ALM1 | ALM0 | 10-da | y digit | | 1-day | digit | | 01-31 | Day alarm |
| 8 | 0 | | 0 | | 0 | Day-o | of-week di | igit | 01-07 | Day-of-week |
| 9 | 0 | 0 | 0 | 10 mo. | | 1-mont | h digit | | 01-12 | Month |
| Α | | 10-yeai | digit | | | 1-year | digit | | 00–99 | Year |
| В | * | WD2 | WD1 | WD0 | RS3 | RS2 | RS1 | RS0 | | Programmable rates |
| С | * | | * | | AIE | PIE | PWRIE | ABE | | Interrupt en- ables |
| D | * | | * | | AF | PF | PWRF | BVF | | Flags |
| Е | * | | * | | UTI | STOP | 24/12 | DSE | | Control |
| F | * | * | * | * | * | * | * | * | | Unused |

Table 1. bq4845 Clock and Control Register Map

 Notes:
 * = Unused bits; unwritable and read as 0.

 0 = should be set to 0 for valid time/calendar range.

 Clock calendar data in BCD. Automatic leap year adjustment.

 PM/AM = 1 for PM; PM/AM = 0 for AM.

 DSE = 1 enables daylight savings adjustment.

 24/12 = 1 enables 24-hour data representation; 24/12 = 0 enables 12-hour data representation.

 Day-of-Week coded as Sunday = 1 through Saturday = 7.

 BVF = 1 for valid battery.

 STOP = 1 turns the RTC on; STOP = 0 stops the RTC in back-up mode.

| Bits | Description |
|-----------|---|
| 24/12 | 24- or 12-hour representation |
| ABE | Alarm interrupt enable in battery-backup mode |
| AF | Alarm interrupt flag |
| AIE | Alarm interrupt enable |
| ALM0-ALM1 | Alarm mask bits |
| BVF | Battery-valid flag |
| DSE | Daylight savings time enable |
| PF | Periodic interrupt flag |
| PIE | Periodic interrupt enable |
| PM/AM | PM or AM indication |
| PWRF | Power-fail interrupt flag |
| PWRIE | Power-fail interrupt enable |
| RS0-RS3 | Periodic interrupt rate |
| STOP | Oscillator stop and start |
| UTI | Update transfer inhibit |
| WD0 - WD2 | Watchdog time-out rate |

Table 2. Clock and Control Register Bits

the data lines are driven to an indeterminate state until t_{AA} . If the address inputs are changed while \overline{CS} and \overline{OE} remain low, output data remains valid for t_{OH} (output data hold time), but goes indeterminate until the next address access.

Write Mode

The bq4845 is in write mode whenever \overline{WE} and \overline{CS} are active. The start of a write is referenced from the latter-occurring falling edge of \overline{WE} or \overline{CS} . A write is terminated by the earlier rising edge of \overline{WE} or \overline{CS} . The addresses must be held valid throughout the cycle. \overline{CS} or \overline{WE} must return high for a minimum of twR2 from \overline{CS} or twR1 from \overline{WE} prior to the initiation of another read or write cycle.

Data-in must be valid t_{DW} prior to the end of write and remain valid for t_{DH1} or t_{DH2} afterward. OE should be kept high during write cycles to avoid bus contention; although, if the output bus has been activated by a low on \overline{CS} and \overline{OE} , a low on WE disables the outputs t_{WZ} after WE falls.

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Reading the Clock

Once every second, the user-accessible clock/calendar locations are updated simultaneously from the internal real time counters. To prevent reading data in transition, updates to the bq4845 clock registers should be halted. Updating is halted by setting the update transfer inhibit (UTI) bit D3 of the control register E. As long as the UTI bit is 1, updates to user-accessible clock locations are inhibited. Once the frozen clock information is retrieved by reading the appropriate clock memory locations, the UTI bit should be reset to 0 in order to allow updates to occur from the internal counters. Because the internal counters are not halted by setting the UTI bit, reading the clock locations has no effect on clock accuracy. Once the UTI bit is reset to 0, the internal registers update within one second the user-accessible registers with the correct time. A halt command issued during a clock update allows the update to occur before freezing the data.

Setting the Clock

The UTI bit must also be used to set the bq4845 clock. Once set, the locations can be written with the desired information in BCD format. Resetting the UTI bit to 0 causes the written values to be transferred to the internal clock counters and allows updates to the useraccessible registers to resume within one second.

Stopping and Starting the Clock Oscillator

The bq4845 clock can be programmed to turn off when the part goes into battery back-up mode by setting STOP to 0 prior to power down. If the board using the bq4845 is to spend a significant period of time in storage, the STOP bit can be used to preserve some battery capacity. STOP set to 1 keeps the clock running when V_{CC} drops below V_{SO}. With V_{CC} greater than V_{SO}, the bq4845 clock runs regardless of the state of STOP.

Power-Down/Power-Up Cycle

The bq4845 continuously monitors V_{CC} for out-oftolerance. During a power failure, when V_{CC} falls below V_{PFD} , the bq4845 write-protects the clock and storage registers. When V_{CC} is below V_{BC} (3V typical), the power source is switched to BC. RTC operation and storage data are sustained by a valid backup energy source. When V_{CC} is above V_{BC} , the power source is V_{CC} . Write-protection continues for t_{CSR} time after V_{CC} rises above V_{PFD} .

An external CMOS static RAM is battery-backed using the V_{OUT} and chip enable output pins from the bq4845. As the voltage input V_{CC} slews down during a power failure, the chip enable output, \overline{CE}_{OUT} , is forced inactive independent of the chip enable input \overline{CE}_{IN} .

This activity unconditionally write-protects the external SRAM as V_{CC} falls below V_{PFD} . If a memory access is in progress to the external SRAM during power-fail detection, that memory cycle continues to completion before the memory is write-protected. If the memory cycle is not terminated within time t_{WPT}, the chip enable output is unconditionally driven high, write-protecting the controlled SRAM.

As the supply continues to fall past V_{PFD} , an internal switching device forces V_{OUT} to the external backup energy source. $\overrightarrow{CE}_{OUT}$ is held high by the V_{OUT} energy source.

During power-up, V_{OUT} is switched back to the 5V supply as V_{CC} rises above the backup cell input voltage sourcing V_{OUT} . $\overrightarrow{CE}_{OUT}$ is held inactive for time t_{CER} after the power supply has reached V_{PFD} , independent of the \overrightarrow{CE}_{IN} input, to allow for processor stabilization.

During power-valid operation, the \overline{CE}_{IN} input is passed through to the \overline{CE}_{OUT} output with a propagation delay of less than 12ns.

Figure 2 shows the hardware hookup for the external RAM, battery, and crystal.

A primary backup energy source input is provided on the bq4845. The BC input accepts a 3V primary battery, typically some type of lithium chemistry. Since the bq4845 provides for reverse battery charging protection, no diode or current limiting resistor is needed in series with the cell. To prevent battery drain when there is no valid data to retain, V_{OUT} and CE_{OUT} are internally isolated from BC by the initial connection of a battery. Following the first application of V_{CC} above V_{PFD}, this isolation is <u>broken</u>, and the backup cell provides power to V_{OUT} and CE_{OUT} for the external SRAM.

The crystal should be located as close to X1 and X2 as possible and meet the specifications in the Crystal Specification Table. With the specified crystal, the bq4845 RTC will be accurate to within one minute per month at room temperature. In the absence of a crystal, a 32.768 kHz waveform can be fed into X1 with X2 grounded.

Power-On Reset

<u>The</u> bq4845 provides a power-on reset, which pulls the RST pin low on power-down and remains low on powerup for t_{RST} after V_{CC} passes V_{PFD}. With valid battery voltage on BC, RST remains valid for V_{CC}= V_{SS}.

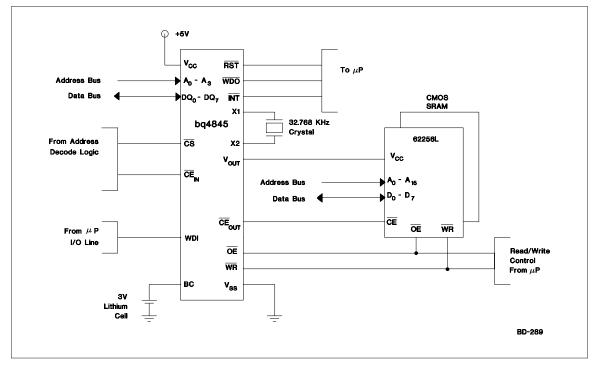


Figure 2. bq4845 Application Circuit

Watchdog Timer

The watchdog monitors microprocessor activity through the Watchdog input (WDI). To use the watchdog function, connect WDI to a bus line or a microprocessor I/O line. If WDI remains high or low for longer than the watchdog time-out period (1.5 seconds default), the bq4845 asserts WDO and $\overline{\text{RST}}$.

Watchdog Input

The bq4845 resets the watchdog timer if a change of state (high to low, low to high, or a minimum 100ns pulse) occurs at the Watchdog input (WDI) during the watchdog period. The watchdog time-out is set by WD0-WD2 in register B. The bq4845 maintains the watchdog time-out programming through power cycles. The default state (no valid battery power) of WD0-WD2 is 000 or 1.5s on power-up. Table 3 shows the programmable watchdog time-out rates. The watchdog time-out period immediately after a reset is equal to the programmed watchdog time-out.

To disable the watchdog function, leave WDI floating. An internal resistor network ($100k\Omega$ equivalent impedance

at WDI) biases WDI to approximately 1.6V. Internal comparators detect this level and disable the watchdog timer. When V_{CC} is below the power-fail threshold, the bq4845 disables the watchdog function and disconnects WDI from its internal resistor network, thus making it high impedance.

Watchdog Output

The Watchdog output (\overline{WDO}) remains high if there is a transition or pulse at WDI during the watchdog timeout <u>period</u>. The bq4845 disables the watchdog function and \overline{WDO} is a logic high when V_{CC} is below the power fail threshold, battery-backup mode is enabled, or WDI is an open circuit. In watchdog mode, if no transition occurs at WDI during the watchdog time-out period, the <u>bq4845</u> asserts RST for the reset time-out period t₁. WDO goes low and remains low until the next transition at WDI. If WDI is held high or low indefinitely, RST will generate pulses (t₁ seconds wide) every t₃ seconds. Figure 3 shows the watchdog timing.

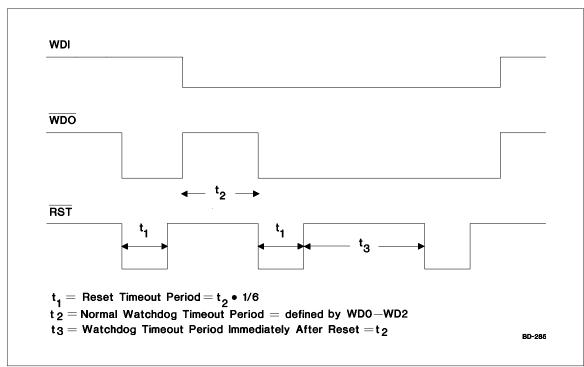


Figure 3. Watchdog Time-out Period and Reset Active Time

Interrupts

The bq4845 allows three individually selected interrupt events to generate an interrupt request on the \overline{INT} pin. These three interrupt events are:

- The periodic interrupt, programmable to occur once every 30.5µs to 500ms
- The alarm interrupt, programmable to occur once per second to once per month
- The power-fail interrupt, which can be enabled to be asserted when the bq4845 detects a power failure

The periodic, alarm, and power-fail interrupts are enabled by an individual interrupt-enable bit in register C, the interrupts register. When an event occurs, its event flag bit in the flags register, register D, is set. If the corresponding event enable bit is also set, then an interrupt request is generated. Reading the flags register clears all flag bits and makes INT high impedance. To reset the flag register, the bq4845 addresses must be held stable at register D for at least 50ns to avoid inadvertent resets.

Periodic Interrupt

Bits RS3–RS0 in the interrupts register program the rate for the periodic interrupt. The user can interpret the interrupt in two ways: either by polling the flags register for PF assertion or by setting PIE so that INT goes active when the bq4845 sets the periodic flag. Reading the flags register resets the PF bit and returns INT to the high-impedance state. Table 4 shows the periodic rates.

Alarm Interrupt

Registers 1, 3, 5, and 7 program the real-time clock alarm. During each update cycle, the bq4845 compares the date, hours, minutes, and seconds in the clock regis-

ters with the corresponding alarm registers. If a match between all the corresponding bytes is found, the alarm flag AF in the flags register is set. If the alarm interrupt is <u>enabled</u> with AIE, an interrupt request is generated on INT. The alarm condition is cleared by a read to the flags register. ALM1 – ALM0 in the alarm registers, mask each alarm compare byte. An alarm byte is masked by setting ALM1 (D7) and ALM0 (D6) to 1. Alarm byte masking can be used to select the frequency of the alarm interrupt, according to Table 5.

The alarm interrupt can be made active while the bq4845 is in the battery-backup mode by setting ABE in the interrupts register. Normally, the \overline{INT} pin goes high-impedance during battery backup. With ABE set, however, \overline{INT} is driven low if an alarm condition occurs and the AIE bit is set. Because the AIE bit is reset during power-on reset updates only the flags register. The user can read the flags register during boot-up to determine if an alarm was generated during power-on reset.

Power-Fail Interrupt

When V_{CC} falls to the power-fail-detect point, the power-fail flag PWRF is set. If the <u>power</u>-fail interrupt enable bit (PWRIE) is also set, then <u>INT</u> is asserted low. The power-fail interrupt occurs t_{WPT} before the bq4845 generates a reset and deselects. The PWRIE bit is cleared on power-up.

Battery-Low Warning

The bq4845 checks the battery on power-up. When the battery voltage is approximately 2.1V, the battery-valid flag BVF in the flags register is set to a 0 indicating that clock and RAM data may be invalid.

| WD2 | WD1 | WD0 | Normal Watchdog Time-out Period (t ₂ , t ₃) | Reset Time-out Period (t ₁) |
|----------|-----|-----|---|--|
| 0 | 0 | 0 | 1.5s | 0.25s |
| 0 | 0 | 1 | 23.4375ms | 3.9063ms |
| 0 | 1 | 0 | 46.875ms | 7.8125ms |
| 0 | 1 | 1 | 93.75ms | 15.625ms |
| 1 | 0 | 0 | 187.5ms | 31.25ms |
| 1 | 0 | 1 | 375ms | 62.5ms |
| 1 | 1 | 0 | 750ms | 125ms |
| 1 | 1 | 1 | 3s | 0.5s |
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Table 3. Watchdog Time-out Rates

| | Registe | er B Bits | | Periodic In | terrupt |
|-----|---------|-----------|-----|-------------|---------|
| RS3 | RS2 | RS1 | RS0 | Period | Units |
| 0 | 0 | 0 | 0 | None | |
| 0 | 0 | 0 | 1 | 30.5175 | μs |
| 0 | 0 | 1 | 0 | 61.035 | μs |
| 0 | 0 | 1 | 1 | 122.070 | μs |
| 0 | 1 | 0 | 0 | 244.141 | μs |
| 0 | 1 | 0 | 1 | 488.281 | μs |
| 0 | 1 | 1 | 0 | 976.5625 | μs |
| 0 | 1 | 1 | 1 | 1.95315 | ms |
| 1 | 0 | 0 | 0 | 3.90625 | ms |
| 1 | 0 | 0 | 1 | 7.8125 | ms |
| 1 | 0 | 1 | 0 | 15.625 | ms |
| 1 | 0 | 1 | 1 | 31.25 | ms |
| 1 | 1 | 0 | 0 | 62.5 | ms |
| 1 | 1 | 0 | 1 | 125 | ms |
| 1 | 1 | 1 | 0 | 250 | ms |
| 1 | 1 | 1 | 1 | 500 | ms |

Table 4. Periodic Interrupt Rates

Table 5. Alarm Frequency (Alarm Bits D6 and D7 of Alarm Registers)

| 1h | 3h | 5h | 7h | |
|-----------|-----------|-----------|-----------|---|
| ALM1•ALM0 | ALM1•ALM0 | ALM1•ALM0 | ALM1•ALM0 | Alarm Frequency |
| 1 | 1 | 1 | 1 | Once per second |
| 0 | 1 | 1 | 1 | Once per minute when seconds match |
| 0 | 0 | 1 | 1 | Once per hour when minutes, and seconds match |
| 0 | 0 | 0 | 1 | Once per day when hours, minutes, and seconds match |
| 0 | 0 | 0 | 0 | When date, hours, minutes, and seconds match |

| Symbol | Parameter | Value | Unit | Conditions |
|----------------------------|---|-------------|------|-------------------------|
| Vcc | DC voltage applied on V_{CC} relative to V_{SS} | -0.3 to 7.0 | V | |
| VT | DC voltage applied on any pin excluding V_{CC} relative to $V_{\rm SS}$ | -0.3 to 7.0 | V | $V_T\!\leq\!V_{CC}+0.3$ |
| TOPR Operating temperature | Operating temperature | 0 to +70 | °C | Commercial |
| TOPK | Operating temperature | -40 to +85 | °C | Industrial |
| T _{STG} | Storage temperature | -55 to +125 | °C | |
| T _{BIAS} | Temperature under bias | -40 to +85 | °C | |
| TSOLDER | Soldering temperature | +260 | °C | For 10 seconds |

Absolute Maximum Ratings

Note: Permanent device damage may occur if **Absolute Maximum Ratings** are exceeded. Functional operation should be limited to the Recommended DC Operating Conditions detailed in this data sheet. Exposure to conditions beyond the operational limits for extended periods of time may affect device reliability.

Recommended DC Operating Conditions (TA = TOPR)

| Symbol | Parameter | Minimum | Typical | Maximum | Unit | Notes |
|-----------------|---------------------|---------|---------|-----------------------|------|---------|
| Vcc | Supply voltage | 4.5 | 5.0 | 5.5 | V | bq4845Y |
| VCC | Supply voltage | 4.75 | 5.0 | 5.5 | v | bq4845 |
| Vss | Supply voltage | 0 | 0 | 0 | v | |
| VIL | Input low voltage | -0.3 | - | 0.8 | V | |
| VIH | Input high voltage | 2.2 | - | V _{CC} + 0.3 | V | |
| V _{BC} | Backup cell voltage | 2.3 | - | 4.0 | V | |

Note: Typical values indicate operation at $T_A = 25^{\circ}C$.

| Symbol | Parameter | Minimum | Typical | Maximum | Unit | Conditions/Notes |
|-------------------|-----------------------------|------------------------|-----------------|---------|------|--|
| I _{LI} | Input leakage current | - | - | ± 1 | μA | $V_{IN} = V_{SS}$ to V_{CC} |
| I _{LO} | Output leakage current | - | - | ± 1 | μΑ | $\overline{CS} = V_{IH} \text{ or } \overline{OE} = V_{IH} \text{ or } \overline{WE}$ $= V_{IL}$ |
| Voh | Output high voltage | 2.4 | - | - | V | I _{OH} = -2.0 mA |
| V _{OHB} | V _{OH.} BC Supply | V _{BC} - 0.3 | - | - | V | $V_{BC} > V_{CC}$, $I_{OH} = -10 \mu A$ |
| VOL | Output low voltage | - | - | 0.4 | V | $I_{OL} = 4.0 \text{ mA}$ |
| I _{CC} | Operating supply current | - | 12 | 25 | mA | $\frac{Min.\ cycle,\ duty\ =\ 100\%,}{\overline{CS}\ =\ V_{IL},\ I_{I/O}\ =\ 0mA}$ |
| I _{SB1} | Standby supply current | - | 3 | - | mA | $\overline{\text{CS}} = \text{V}_{\text{IH}}$ |
| I _{SB2} | Standby supply current | - | 1.5 | - | mA | $\label{eq:cs} \begin{split} \overline{CS} &\geq V_{CC} - 0.2V, \\ 0V &\leq V_{IN} \leq \ 0.2V, \\ \text{or} \ V_{IN} &\geq V_{CC} - 0.2V \end{split}$ |
| V _{SO} | Supply switch-over voltage | - | V _{BC} | - | V | |
| I _{CCB} | Battery operation current | - | 0.3 | 0.5 | μΑ | V_{BC} = 3V, $T_{\underline{A}}$ = 25°C, no load on V_{OUT} or \overline{CE}_{OUT} |
| X 7 | Power-fail-detect voltage | 4.55 | 4.62 | 4.75 | V | bq4845 |
| VPFD | Power-fail-detect voltage | 4.30 | 4.37 | 4.5 | V | bq4845Y |
| V _{OUT1} | V _{OUT} voltage | V _{CC} - 0.3V | - | - | V | I_{OUT} = 100mA, $V_{CC} > V_{BC}$ |
| V _{OUT2} | V _{OUT} voltage | V _{BC} - 0.3V | - | - | V | I_{OUT} = 100 μ A, V_{CC} < V_{BC} |
| V _{RST} | RST output voltage | - | - | 0.4V | - | $I_{RST} = 4mA$ |
| VINT | INT output voltage | - | - | 0.4V | - | $I_{INT} = 4mA$ |
| V | WDO sutput volto se | - | - | 0.4V | - | $I_{SINK} = 4mA$ |
| V _{WDO} | WDO output voltage | 2.4 | - | - | - | $I_{SOURCE} = 2mA$ |
| IWDIL | Watchdog input low current | -50 | -10 | - | μA | $0 < V_{WDI} < 0.8 \mathrm{V}$ |
| I _{WDIH} | Watchdog input high current | - | 20 | 50 | μA | $2.2 < V_{WDI} < V_{CC}$ |

DC Electrical Characteristics (TA = TOPR, VCCmin \leq VCC \leq VCCmax)

Notes: Typical values indicate operation at $T_A = 25^{\circ}C$, $V_{CC} = 5V$. RST and \overline{INT} are open-drain outputs.

Crystal Specifications (DT-26 or Equivalent)

| Symbol | Parameter | Minimum | Typical | Maximum | Unit |
|----------------|------------------------------|---------|---------|---------|--------|
| fo | Oscillation frequency | - | 32.768 | - | kHz |
| CL | Load capacitance | - | 6 | - | pF |
| TP | Temperature turnover point | 20 | 25 | 30 | °C |
| k | Parabolic curvature constant | - | - | -0.042 | ppm/°C |
| Q | Quality factor | 40,000 | 70,000 | - | |
| R ₁ | Series resistance | - | - | 45 | KΩ |
| C ₀ | Shunt capacitance | - | 1.1 | 1.8 | pF |
| C_0/C_1 | Capacitance ratio | - | 430 | 600 | |
| DL | Drive level | - | - | 1 | μW |
| $\Delta f/f_O$ | Aging (first year at 25°C) | - | 1 | - | ppm |

Capacitance (T_A = 25°C, F = 1MHz, V_{CC} = 5.0V)

| Symbol | Parameter | Minimum | Typical | Maximum | Unit | Conditions |
|------------------|--------------------------|---------|---------|---------|------|---------------------|
| C _{I/O} | Input/output capacitance | - | - | 7 | pF | Output voltage = 0V |
| C _{IN} | Input capacitance | - | - | 5 | pF | Input voltage = 0V |

Note: These parameters are sampled and not 100% tested.

AC Test Conditions

| Parameter | Test Conditions |
|--|------------------------------------|
| Input pulse levels | 0V to 3.0V |
| Input rise and fall times | 5 ns |
| Input and output timing reference levels | 1.5 V (unless otherwise specified) |
| Output load (including scope and jig) | See Figures 4 and 5 |

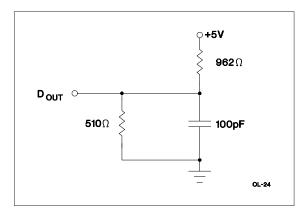


Figure 4. Output Load A

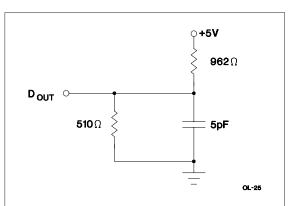


Figure 5. Output Load B

Read Cycle (TA = TOPR, VCCmin \leq VCC \leq VCCmax)

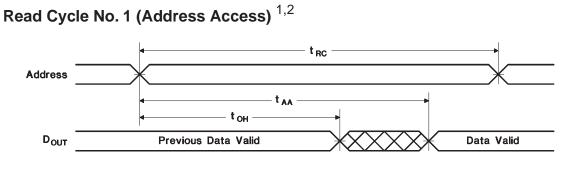
| Symbol | Parameter | Min. | Max. | Unit | Conditions |
|------------------|------------------------------------|------|------|------|---------------|
| t _{RC} | Read cycle time | 70 | - | ns | |
| t _{AA} | Address access time | - | 70 | ns | Output load A |
| t _{ACS} | Chip select access time | - | 70 | ns | Output load A |
| toE | Output enable to output valid | - | 35 | ns | Output load A |
| t _{CLZ} | Chip select to output in low Z | 5 | - | ns | Output load B |
| toLZ | Output enable to output in low Z | 0 | - | ns | Output load B |
| t _{CHZ} | Chip deselect to output in high Z | 0 | 25 | ns | Output load B |
| t _{OHZ} | Output disable to output in high Z | 0 | 25 | ns | Output load B |
| toH | Output hold from address change | 10 | - | ns | Output load A |

Write Cycle (TA =TOPR, VCCmin \leq VCC \leq VCCmax)

| Symbol | Parameter | Min. | Max. | Unit | Conditions |
|------------------|-------------------------------------|------|------|------|---|
| twc | Write cycle time | 70 | - | ns | |
| t _{CW} | Chip select to end of write | 65 | - | ns | (1) |
| t _{AW} | Address valid to end of write | 65 | - | ns | (1) |
| t _{AS} | Address setup time | 0 | - | ns | Measured from address valid to beginning of write. (2) |
| t _{WP} | Write pulse width | 55 | - | ns | Measured from beginning of write to end of write. (1) |
| t _{WR1} | Write recovery time (write cycle 1) | 5 | - | ns | Measured from $\overline{\text{WE}}$ going high to end of write cycle. (3) |
| t _{WR2} | Write recovery time (write cycle 2) | 15 | - | ns | Measured from $\overline{\text{CS}}$ going high to end of write cycle. (3) |
| t _{DW} | Data valid to end of write | 30 | - | ns | Measured to first low-to-high transition of either $\overline{\text{CS}}$ or $\overline{\text{WE}}$. |
| t _{DH1} | Data hold time (write cycle 1) | 0 | - | ns | Measured from $\overline{\text{WE}}$ going high to end of write cycle. (4) |
| t _{DH2} | Data hold time (write cycle 2) | 10 | - | ns | Measured from \overline{CS} going high to end of write cycle. (4) |
| t _{WZ} | Write enabled to output in high Z | 0 | 25 | ns | I/O pins are in output state. (5) |
| tow | Output active from end of write | 0 | - | ns | I/O pins are in output state. (5) |

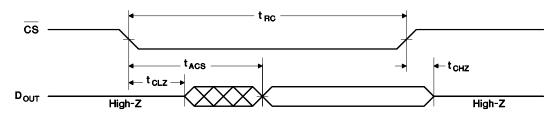
Notes: 1. A write ends at the earlier transition of \overline{CS} going high and \overline{WE} going high.

- 2. A write occurs during the overlap of a low \overline{CS} and a low \overline{WE} . A write begins at the later transition of \overline{CS} going low and \overline{WE} going low.
- 3. Either t_{WR1} or t_{WR2} must be met.
- 4. Either t_{DH1} or t_{DH2} must be met.
- 5. If $\overline{\text{CS}}$ goes low simultaneously with $\overline{\text{WE}}$ going low or after $\overline{\text{WE}}$ going low, the outputs remain in high-impedance state.



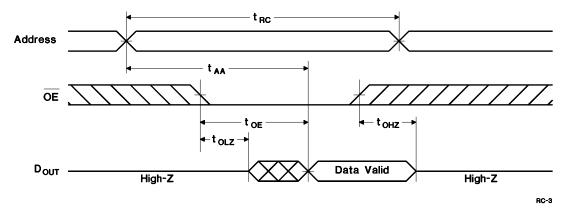
RC-1

Read Cycle No. 2 (CS Access) ^{1,3,4}



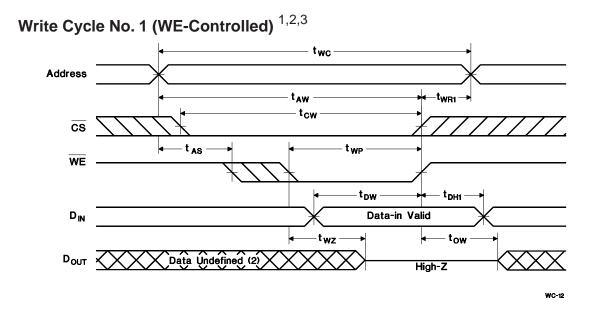
RC-36

Read Cycle No. 3 (OE Access) ^{1,5}

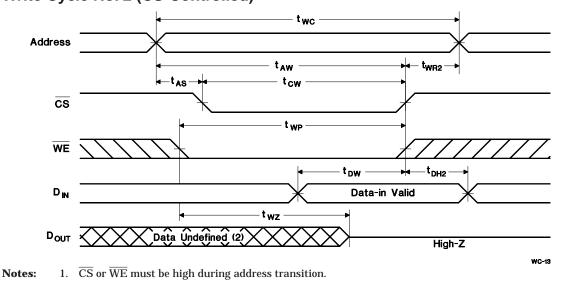


Notes: 1. \overline{WE} is held high for a read cycle.

- 2. Device is continuously selected: $\overline{CS} = \overline{OE} = V_{IL}$.
- 3. Address is valid prior to or coincident with $\overline{\text{CS}}$ transition low.
- $4. \quad \overline{OE} = V_{IL}.$
- 5. Device is continuously selected: \overline{CS} = $V_{IL}.$



Write Cycle No. 2 (CS-Controlled) ^{1,2,3,4,5}



2. Because I/O may be active (\overline{OE} low) during this period, data input signals of opposite polarity to the outputs must not be applied.

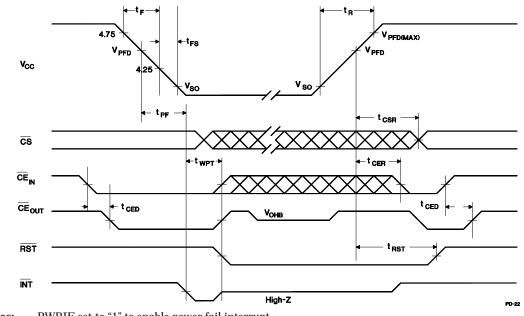
- 3. If $\overline{\text{OE}}$ is high, the I/O pins remain in a state of high impedance.
- 4. Either t_{WR1} or t_{WR2} must be met.
- 5. Either t_{DH1} or t_{DH2} must be met.

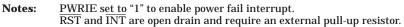
| Symbol | Parameter | Minimum | Typical | Maximum | Unit | Conditions |
|------------------|---|------------------|---------|------------------|------|---|
| t _F | V _{CC} slew from 4.75 to 4.25V | 300 | - | - | μs | |
| t _{FS} | V_{CC} slew from 4.25 to V_{SO} | 10 | - | - | μs | |
| t _R | V _{CC} slew from V _{SO} to V _{PFD(MAX)} | 100 | - | - | μs | |
| t _{PF} | Interrupt delay from V_{PFD} | 6 | - | 24 | μs | |
| t _{WPT} | Write-protect time for external RAM | 90 | 100 | 125 | μs | Delay after V_{CC} slews down past V_{PFD} before SRAM is write-protected and \overline{RST} activated. |
| t _{CSR} | $\overline{\text{CS}}$ at V_{IH} after power-up | 100 | 200 | 300 | ms | Internal write-protection period after V_{CC} passes V_{PFD} on power-up. |
| t _{RST} | V_{PFD} to $\overline{\text{RST}}$ inactive | t _{CSR} | - | t _{CSR} | ms | Reset active time-out period |
| t _{CER} | Chip enable recovery time | t _{CSR} | - | t _{CSR} | ms | Time during which external SRAM is write-protected after $V_{\rm CC}$ passes $V_{\rm PFD}$ on power-up. |
| t _{CED} | Chip enable propagation delay to external SRAM | - | 9 | 12 | ns | Output load A |

Power-Down/Power-Up Timing (TA = TOPR)

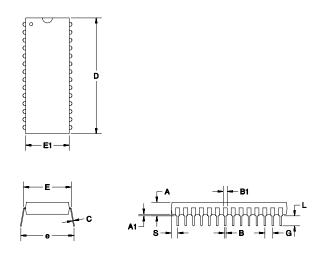
Caution: Negative undershoots below the absolute maximum rating of -0.3V in battery-backup mode may affect data integrity.

Power-Down/Power-Up Timing





28-Pin DIP (P)

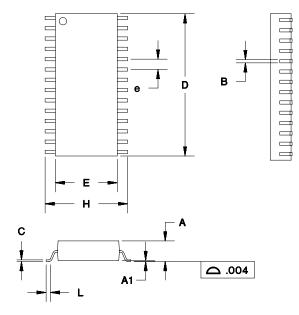


| Dimension | Minimum | Maximum | | | | | | |
|-----------|---------|---------|--|--|--|--|--|--|
| A | 0.160 | 0.190 | | | | | | |
| A1 | 0.015 | 0.040 | | | | | | |
| В | 0.015 | 0.022 | | | | | | |
| B1 | 0.045 | 0.065 | | | | | | |
| С | 0.008 | 0.013 | | | | | | |
| D | 1.440 | 1.480 | | | | | | |
| Е | 0.600 | 0.625 | | | | | | |
| E1 | 0.530 | 0.570 | | | | | | |
| е | 0.600 | 0.670 | | | | | | |
| G | 0.090 | 0.110 | | | | | | |
| L | 0.115 | 0.150 | | | | | | |
| S | 0.070 | 0.090 | | | | | | |

28-Pin DIP (P)

All dimensions are in inches.

28-Pin SOIC (S)

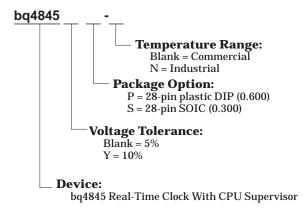


| 28-Pin SOIC (S) | | | | | | | |
|-----------------|---------|--|--|--|--|--|--|
| Dimension | Minimum | | | | | | |
| Δ | 0.005 | | | | | | |

| Dimension | Minimum | Maximum |
|-----------|---------|---------|
| Α | 0.095 | 0.105 |
| A1 | 0.004 | 0.012 |
| В | 0.013 | 0.020 |
| С | 0.008 | 0.013 |
| D | 0.700 | 0.715 |
| E | 0.290 | 0.305 |
| e | 0.045 | 0.055 |
| Н | 0.395 | 0.415 |
| L | 0.020 | 0.040 |

All dimensions are in inches.

Ordering Information



PACKAGING INFORMATION

| Orderable Device | Status ⁽¹⁾ | Package Type | Package Drawing | Pins | Package Qty | Eco Plan ⁽²⁾ | Lead/Ball Finish | MSL Peak Temp ⁽³⁾ |
|------------------|-----------------------|-----------------|--------------------|------|----------------|-------------------------|------------------|------------------------------|
| BQ4845P-A4 | ACTIVE | PDIP | Ν | 28 | 13 | TBD | Call TI | Level-NA-NA-NA |
| BQ4845S-A4 | ACTIVE | SOIC | DW | 28 | 20 | TBD | CU NIPDAU | Level-1-220C-UNLIM |
| BQ4845S-A4N | ACTIVE | SOIC | DW | 28 | 20 | TBD | CU NIPDAU | Level-1-220C-UNLIM |
| BQ4845S-A4NTR | ACTIVE | SOIC | DW | 28 | 1000 | TBD | CU NIPDAU | Level-1-220C-UNLIM |
| BQ4845S-A4TR | ACTIVE | SOIC | DW | 28 | 1000 | TBD | CU NIPDAU | Level-1-220C-UNLIM |
| BQ4845YP-A4 | ACTIVE | PDIP | Ν | 28 | 13 | TBD | Call TI | Level-NA-NA-NA |
| BQ4845YS-A4 | ACTIVE | SOIC | DW | 28 | 20 | TBD | CU NIPDAU | Level-1-220C-UNLIM |
| BQ4845YS-A4N | ACTIVE | SOIC | DW | 28 | 20 | TBD | CU NIPDAU | Level-1-220C-UNLIM |
| BQ4845YS-A4NTR | ACTIVE | SOIC | DW | 28 | 1000 | TBD | CU NIPDAU | Level-1-220C-UNLIM |
| BQ4845YS-A4TR | ACTIVE | SOIC | DW | 28 | 1000 | TBD | CU NIPDAU | Level-1-220C-UNLIM |

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS) or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details. TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

⁽³⁾ MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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Mailing Address:

Texas Instruments

Post Office Box 655303 Dallas, Texas 75265

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