Absolute 60-mm-dia. Rotary Encoder

# E6F-A

## **Rugged Encoder for High-precision Detection of Automatic Machine** Timing

- Rugged construction with the highest shaft loading. Radial: 120 N, Thrust: 50 N
- IP65f water- and oil-proof construction.
- Support for more applications with a wider range of resolutions. (E6F-AG5C-C: Resolutions up to 720)
- Higher response speed for faster control. (Gray code: 20 kHz)



Rotary Encoders

Be sure to read Safety Precautions on page 1072.

## **Ordering Information**

## Sensing Guide

Unit

Other

Guide	Encoder					
	Power supply voltage	Output configuration	Output code	<b>Resolution (pulses/rotation)</b>	Connection method	Model
Encoders					Pre-wired Model	E6F-AB3C*3
LICOUCIS	51012 000		BCD	360	Connector Models	E6F-AB3C-C *1, *3
Absolute	12 to 24 VDC	NFN Open collector			Pre-wired Model	E6F-AB5C
Encoders					Connector Models	E6F-AB5C-C
E		PNP open collector			Pre-wired Model	E6F-AB5B
Easy Scale Direction Discrimination		NPN open collector G		256, 360, 720	Connector Models	E6F-AG5C-C*2
			Gray code	256, 360, 720, 1,024	Pre-wired Model	E6F-AG5C
		PNP open collector				E6F-AG5B

Note: When ordering, specify the resolution in addition to the model number (example: E6F-AG5C 256 P/R).

\*1. The E6F-AB3C-C is designed for connection to Rotary Positioners (H8PR-8, -16, -24).
\*2. The E6F-AG5C-C is designed for connection to Cam Positioners (H8PS).
\*3. Models are also available with 5-m and 10-m cables.

Peripheral Devices

### Accessories (Order Separately)

Information							
IIII0IIIalloII	Name	Model		Remarks			
		E69-C10B	Provided w	vith E6F Pre-wired Models.			
	Couplings	E69-C610B	Different end diameter				
		E69-C10M	Metal construction				
	Servo Mounting Bracket	E69-2	Provided w	vith the product. (Three brackets in a set.)			
		E69-DF5	5 m				
E6C-N E6CP-A	Extension Cable	E69-DF10	10 m	Models are also available with 15-m and 98-m cables.			
		E69-DF20	20 m	]			
			-				

For details, refer to Accessories on page 1082.

E6C3-A E6F-A

## **Ratings and Specifications**

Item	Model	E6F- AB3C-C	E6F- AB3C	E6F- AB5C-C	E6F- AB5C	E6F- AB5B	E6F- AG5C-C	E6F- AG5C	E6F- AG5B	
Power supp	ply voltage	5 VDC -5% to 12 VDC +10%, ripple (p-p): 5% max. 12 VDC -10% to 24 VDC +15%, ripple (p-p): 5% max.							-	
Current co	nsumption*1	60 mA max.							-	
Resolution (pulses/rota	ation)*2	360         256, 360, 720         256, 360, 720, 1024					-			
Output cod	le	BCD					Gray code	1		-
Output con	figuration	PNP open- collector         PNP open- collector         PNP open- collector         PNP open- collector         PNP open- collector           vutput         vutput         vutput         vutput         vutput         vutput				PNP open- collector output	-			
Output capacity       Applied voltage: 30 VDC max.       Source current: 35 m         Bink current: 35 mA max.       Residual         Voltage:       0.4 V max.         (at source current of 35 mA)       0.4 V max         (at source current of 35 mA)       0.4 V max			Source cur- rent: 35 mA max. Residual voltage: 0.4 V max. (at source current of 35 mA)	Applied volta max. Sink current: Residual volt max. (at sink curre	ge: 30 VDC 35 mA max. age: 0.4 V nt of 35 mA)	Source cur- rent: 35 mA max. Residual voltage: 0.4 V max. (at source current of 35 mA)				
Maximum r frequency*	response 3	10 kHz					20 kHz			Rotary Encoders
LogicNegative logic (high = 0, low = 1)Positive log- ic (high = 1, low = 0)Negative logic (high = 0, low = 1)Positive ic (high = 1, low = 1)				Positive log- ic (high = 1, low = 0)	-					
Direction o	f rotation	Output code incremented by CW (as viewed from the end of the shaft)							Sensing	
Rise and fall times of output		1 $\mu$ s max. (E6F-AB3C, A $\Box$ 5C: Load voltage: 5 V, Load resistance: 1 k $\Omega$ , Output cable: 2 m max.; E6F-A $\Box$ 5B: Power supply voltage: 12 V, Load resistance: 1 k $\Omega$ , Output cable: 2 m max.)							Guide	
Starting tor	rque	9.8 mN⋅m ma	ax. at room tem	perature, 14.7	mN⋅m max. a	t low temperate	ure			Incrementa
Moment of	inertia	1.5 × 10⁻6 kg·	m² max.							Encoders
Shaft	Radial	120 N								Absolute
loading	Thrust	50 N								Encoders
Maximum p speed	permissible	5000 r/min							Easy	
Ambient te	mperature	Operating: -10 to 70°C (with no icing), Storage: -25 to 80°C (with no icing)							Scale	
Ambient hu	umidity	Operating: 35% to 85% (with no condensation), Storage: 35% to 95% (with no condensation)							Direct	
Insulation r	resistance	20 M $\Omega$ min. (at 500 VDC) between current-carrying parts and case							<ul> <li>Discrimination</li> <li>Unit</li> </ul>	
Dielectric strength		500 VAC, 50/60 Hz for 1 min between current-carrying parts and case							 Deviale and	
Vibration resistance		10 to 500 Hz, 1.5-mm double amplitude for 11 min 3 times each in X, Y, and Z directions						<ul> <li>Periprieral</li> <li>Devices</li> </ul>		
Shock resistance		Destruction: 1,000 m/s <sup>2</sup> 3 times each in X, Y, and Z directions								
Degree of p	protection	IEC 60529 IP65 *4						Other		
Connection method		Connector Models (Standard cable length: 2 m)	Pre-wired Models (Standard cable length: 2 m)	Connector Models (Standard cable length: 2 m)	Pre-wired Mo dard cable le	odels (Stan- ngth: 2 m)	Connector Models (Standard cable length: 2 m)	Pre-wired Mo dard cable le	odels (Stan- ength: 2 m)	
Material		Case: Zinc al	loy, Main unit:	Aluminum, Sh	aft: SUS420J2	, Mounting Bra	acket: Galvaniz	ed iron		-
Weight (pa	cked state)	Approx. 500 g						-		
Accessories		Coupling (provided with Pre-wired Models only), Hexagonal wrench (provided with Pre-wired Models only), Servo Mounting Bracket, Instruction manual						E6C-N		
*1. An inrush c	current of approxim	nately 9 A will flow	w for approximate	ely 5 μs when the	e power is turne	d ON.				E6CP-A

Output code	Resolution	Code No.
BCD	360	0 to 359
	256	0 to 255
Gray and	360	76 to 435 (gray after 76)
Glay Code	720	152 to 871 (gray after 152)
	1024	0 to 1023

\*3. The maximum electrical response speed is determined by the resolution and maximum response frequency as follows:

Maximum response frequency × 60 Maximum electrical response speed (rpm) =

Resolution

\* This means that the Rotary Encoder will not operate electrically if its speed exceeds the maximum electrical response speed. \*4. JEM 1030: Applicable from 1991.

E6C3-A E6F-A

## E6F-A I/O Circuit Diagrams



E6F-A

1070 omron

10-bit

(720,1024)

20

2<sup>1</sup>

2<sup>2</sup>

23

**2**<sup>4</sup>

2<sup>5</sup>

26

27

28

2<sup>9</sup>

E6F-AG5C/-AG5B

Output signal

9-bit (360)

20

2<sup>1</sup>

2<sup>2</sup>

2<sup>3</sup>

**2**<sup>4</sup>

25

26

27

28

Shield (ground)

12 to 24 VDC

0 V (common)

Not connected Not connected

8-bit (256)

20

21

22

2<sup>3</sup>

**2**<sup>4</sup>

25

26

27

Not connected

## **Connection Specifications**

#### **Connector Models\***

Model	E6F-AB3C-C/ -AB5C-C		E6F-AG5C-C			
	Output signal	Output signal				
Pin No.	10-bit (360)	8-bit (256)	9-bit (360)	10-bit (720)		
1	2 <sup>0</sup>	Connected in-	Not connected	2 <sup>9</sup>		
2	2 <sup>1</sup>	ternally	2 <sup>8</sup>	2 <sup>8</sup>		
3	2 <sup>2</sup>	2 <sup>5</sup>	2 <sup>5</sup>	<b>2</b> <sup>5</sup>		
4	2 <sup>3</sup>	2 <sup>1</sup>	2 <sup>1</sup>	2 <sup>1</sup>		
5	$2^{\circ} \times 10$	2 <sup>0</sup>	2 <sup>0</sup>	2 <sup>0</sup>		
6	$2^1 \times 10$	27	27	27		
7	$2^2 \times 10$	2 <sup>4</sup>	2 <sup>4</sup>	24		
8	$2^3 \times 10$	2 <sup>2</sup>	2 <sup>2</sup>	2 <sup>2</sup>		
9	$2^{0}  imes 100$	2 <sup>3</sup>	2 <sup>3</sup>	2 <sup>3</sup>		
10	$2^1  imes 100$	2 <sup>6</sup>	2 <sup>6</sup>	2 <sup>6</sup>		
11		Shield (ground)				
12	-AB3C-C: 5 to 12 VDC, -AB5C- C: 12 to 24 VDC		12 to 24 VDC			
13	0 V (common)		0 V (common)			
12 13	-AB3C-C: 5 to 12 VDC, -AB5C- C: 12 to 24 VDC 0 V (common)		12 to 24 VDC 0 V (common)			

\* Connector: RP13A-12PD-13SC (Hirose Electric Co., Ltd.)

## **Connection Example**

### **H8PR Rotary Positioner Connection**



H8PR-8, -16, -24 Easy-key-switching **Rotary Positioner** C

350 

#### **Ordering Information**

Model	Applicable model
H8PR-8	
H8PR-16	E6F-AB3C-C
H8PR-24	

#### E6F-AB3C-C Rotary Encoder

**Pre-wired Model** 

Model

Wire

color

Brown

Orange

Yellow

Green

Blue

Purple

Gray

White

Pink

Light

blue

---

Red

Black

E6F-AB3C/

-AB5C/-AB5B Output signal

10-bit (360)

20

2<sup>1</sup>

22

23

 $2^{0} \times 10$ 

 $2^1 imes 10$ 

 $2^2 imes 10$ 

 $2^3 \times 10$ 

 $2^{0} \times 100$ 

 $2^1 imes 100$ 

Shield (ground) -AB3C: 5 to 12

VDC, -AB5C: 12

0 V (common)

to 24 VDC

Note: The cable length between the H8PR and E6F-AB3C-C can be extended to a maximum of 30 m.

Peripheral

Information

**Specifications** 

Rated voltage	100 to 240 VAC
Cam precision	1° (360 divisions per revo- lution)
No. of out- put points	H8PR-8: 8 points H8PR-16: 16 points H8PR-24: 24 points
Encoder response	833 r/min
Additional functions	<ul> <li>Origin compensation (zeroing)</li> <li>Rotation direction switching</li> <li>Initial angle specification</li> <li>Angle teaching</li> <li>Retentive memory for power interruptions (10 years min.)</li> </ul>

Rotary Encoders

Sensing Guide

Incremental **Encoders** 

> Absolute Encoders

Easy Scale

Direct Discrimination Unit

Devices

Other

E6C-N E6CP-A E6C3-A E6F-A

### **H8PS Cam Positioner Connection**

### H8PS-8A, -8AF

**Cam Positioner** 



#### **Ordering Information**

Model	Applicable model	
H8PS-8A		
H8PS-8AF	EOF-AG5C-C	

Note: The cable length between the H8PS and
E6F-AG5C-C can be extended to a
maximum of 100 m.

#### **Specifications**

Rated voltage	24 VDC
Cam precision	1.4° (256 divisions per revolu- tion)
No. of output points	8 cam outputs 1 RUN output 1 rotating output
Encoder response	330 r/min
Additional functions	<ul> <li>Origin compensation (zeroing)</li> <li>Rotation direction switch- ing</li> <li>Angle display switching</li> <li>Teaching</li> </ul>

## Rotary Encoders

### Programmable Controller Connection

Connection is possible with the CQM1H-CPU51 and CQM1H-ABB21.

Refer to the CQM1H Programmable Controller Catalog (P050) for details on the CQM1H Programmable Controller.

#### Sensing Safety Precautions Guide

#### Refer to Warranty and Limitations of Liability on page F-2. Incremental

Encodore	, , , , , , , , , , , , , , , , , , , ,
LICOUCIS	M WARNING
Absolute Encoders	This product is not designed or rated for ensuring safety of persons. Do not use it for such purposes.
Easy Scale	
Direction	Precautions for Correct Use
Discrimination Unit	Do not use the Encoder under ambient conditions that exceed the ratings.
Peripheral	Adjustment
Devices	Reading the Output Code
Other Information	Read the code after the LSB (output $2^{0}$ ) of the code changes for the E6F-AB3C and E6F-AB3C-C.
	Wiring
	Spurious pulses may be generated when power is turned ON and

Spurious pulses may be generated when power is turned ON and OFF. Wait at least 0.1 s after turning ON the power to the Encoder before using the connected device, and stop using the connected device at least 0.1 s before turning OFF the power to the Encoder. Also, turn ON the power to the load only after turning ON the power to the Encoder.

## Dimensions

(Unit: mm)



Cat. No. F824-E1-01 In the interest of product improvement, specifications are subject to change without notice.

omron 1073

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### OMRON ELECTRONICS LLC

1 Commerce Drive Schaumburg, IL 60173 Tel: 847.843.7900 For U.S. technical support or other inquiries: 800.556.6766

#### **OMRON CANADA, INC.**

885 Milner Avenue Toronto, Ontario M1B 5V8 Tel: 416.286.6465 MEXICO SALES OFFICES

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