

XC164CM series Easy Kit

Board REV. V2.0 and V2.1

Microcontrollers



Never stop thinking.

XC164CM series Easy Kit

Revision History: **2005-04**

V 1.0

Previous Version: -

Page	Subjects (major changes since last revision)

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1 Introduction

The XC164CM-8FF is a new member of Infineon's XC166 family of 16-bit microcontrollers based on the high-performance C166S V2 core in a sub-0.25 μ technology. The C166S V2 core more than doubles the performance of the well established C166 core while still providing code compatibility.

Applications can be developed easily. The Evaluation Board is equipped with peripherals for connection to the environment. There is also an interface for the On Chip Debugging Features (OCDS1). For programming of the embedded Flash, Infineon provides a tool, called MEMTOOL.

The Evaluation Board allows easily the development of XC164CM family applications with the corresponding tools. Subsequently, the applications can be downloaded and can be tested with the powerful debugger software.

For detailed technical information about the XC164CM please refer to the User's Manual of the XC164CM V1.1 and the Data Sheet V1.1.

To make sure that you always have the latest Dokumentation please contact your local FAE or visit our XC164CM internet homepage:

<http://www.infineon.com/XC164CM>

2 Features of the XC164CM series Easy Kit Board

The XC164CM series Easy Kit is soldert with the XC164CM-8F device. This device fit into all members of this product family so that there are no special Easy Kit Boards necessary.

2.1 Summary of Features

- Infineon’s XC164CM Controller in TQFP64 Package
- On-board dual voltage power supply provides 5V/2.6V to XC164CM
- High Speed CAN Transceivers, LIN Transceiver, UART(RS232)
- 8 Low Power Status LEDs
- Easy access to all pins

Connectors

The XC164CM Board offers a wide variety of connectors:

- SUB-D9 connector for ASC0 Interface via RS 232 port
- 4 pin header for LIN Transceiver (ASC1)
- 16-pin header for JTAG interface (OCDS)
- SUB-D9 connector for CAN High Speed Transceiver (CAN1)
- 10pin (2x5) Header for CAN High Speed Transceiver (CAN2)
- Easy access to all pins

Components

- Dual Low-Drop Voltage Regulator TLE 7469 to supply 5V/2.6V
- Two LEDs to validate power supply (5Volt / 2.6Volt)
- LED indicating /RSTIN active state
- 2 x CAN-Transceiver TLE 6250
- LIN Transceiver TLE 7259
- 8 general purpose LEDs
- Reset switch

Zero Ohm Bridges

- Zero Ohm resistors give the flexibility to configure the systems functionality

2.2 Block Diagram

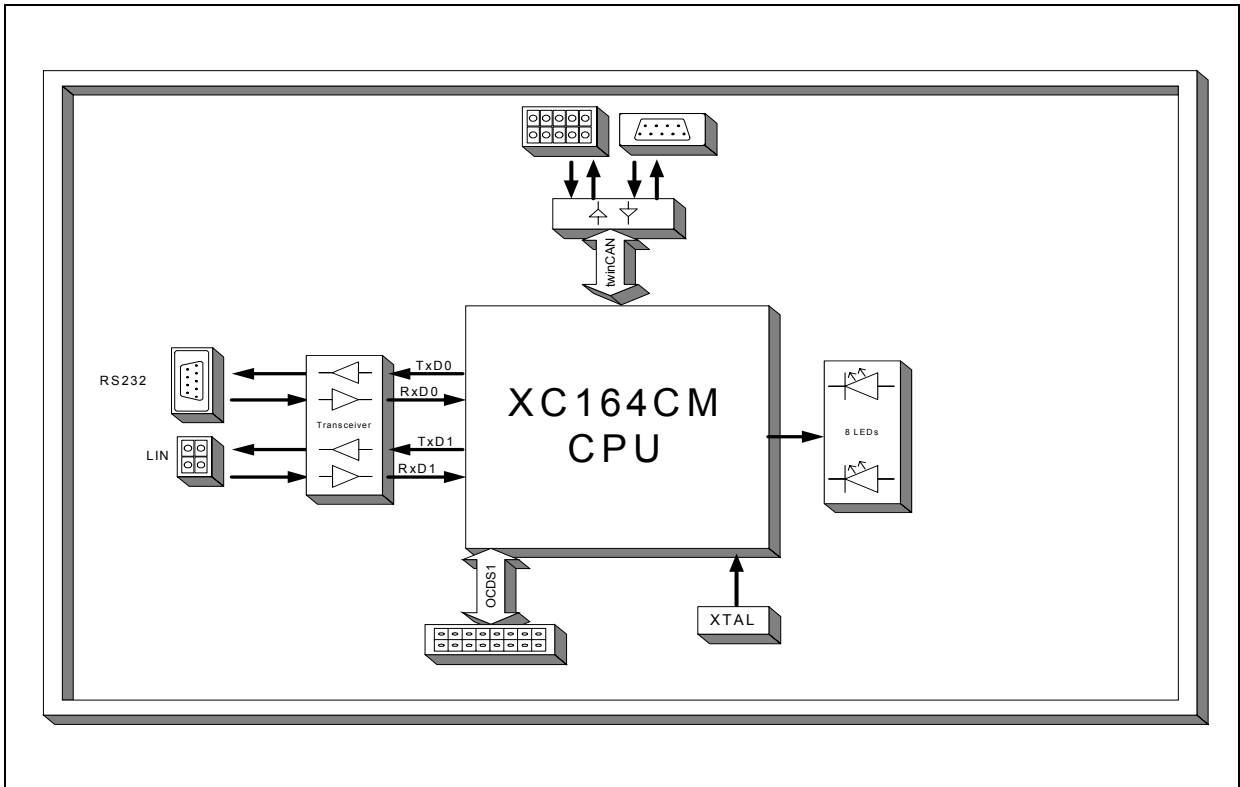


Figure 1 Block diagram of XC164CM Easy Kit

2.3 Layout Overview

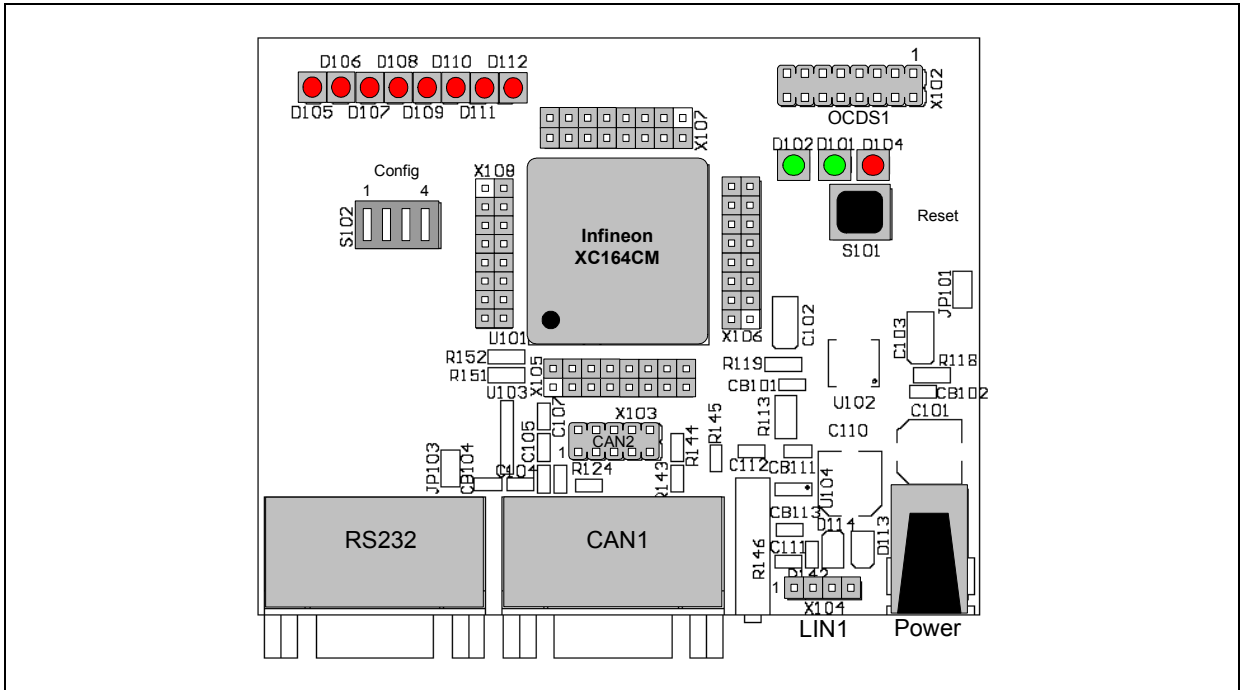


Figure 2 Top view

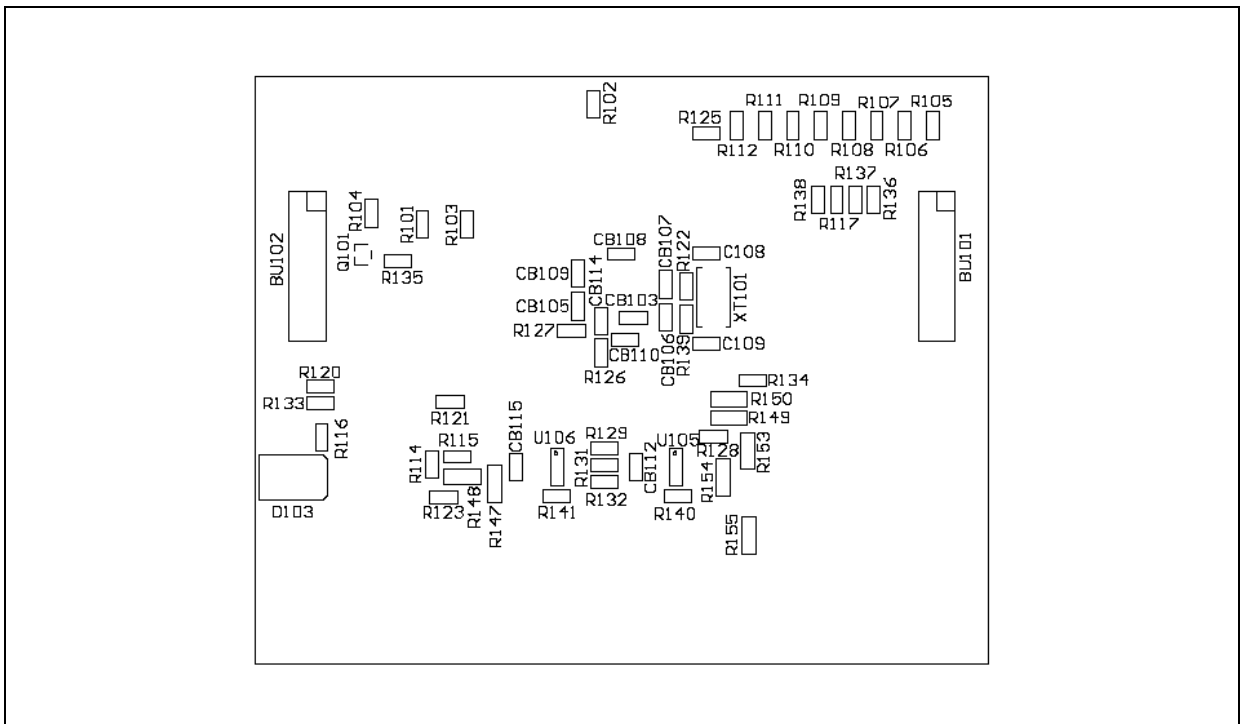


Figure 3 Bottom view

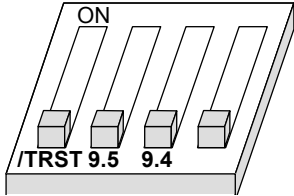
2.4 DIP Switch S102

Although most of the programmable features of the XC164CM are selected by software either during the initialization phase or repeatedly during program execution, some features must be selected earlier because they are used for the first access of the program execution.

These configurations are accomplished by latching the logic levels at a number of pins at the end of the internal reset sequence.

DIP switch S102 allows to configure the startup setting of the XC164CM during RESET. The default System Startup Configuration is shown in [Table 1](#). All DIP Switch are OFF. The XC164CM execute a standard start from internal Flash.

Table 1 Default configuration

Name in schematic	Default configuration	Description
S102		Startup configuration: Standard start from internal Flash (Default)

The pull-ups on the configuration pins are activated while TRST = 1 and the hardware reset signal is active shown in the [Table 2](#) below.

Table 2 Basic Startup Configuration via External Circuitry

XC164CM Pin level configured by S102	Function
/TRST = 0, P9.5 = x, P9.4 = x,	Default standard start internal Flash
/TRST = 1, P9.5 = 1, P9.4 = 1,	Standard start internal Flash
/TRST = 1, P9.5 = 0, P9.4 = 1,	Bootstrap loader via ASC0
/TRST = 1, P9.5 = 1, P9.4 = 0,	Bootstrap loader via CAN
/TRST = 1, P9.5 = 0, P9.4 = 0,	Adapt Mode
All other positions	Reserved

For more detailed information about the DIP switch setting please refer to [Chapter 3.1](#), [Table 3](#).

2.5 Power Supply

The XC164CM Board needs an external power supply. A regulated DC power supply with **max. 12 Volts / 400mA** can be connected to the power connector.

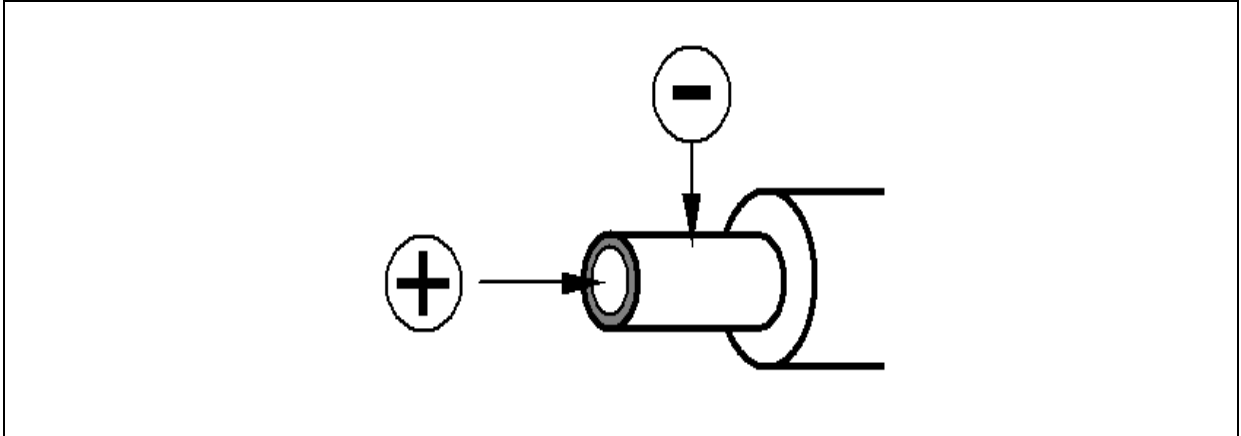


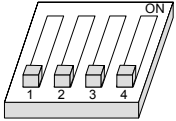
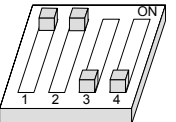
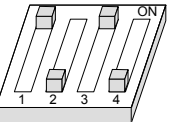
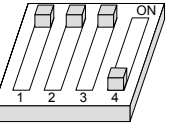
Figure 4 Power Supply

3 Description of Connectors and Switches

The On-Chip Bootstrap Loader allows the start code to be moved into the internal PSRAM of the XC164CM via the serial interface ASC0. The XC164CM will then execute the loaded start code out of the PSRAM.

3.1 Switch S102

Table 3 DIP Switch Settings for S102

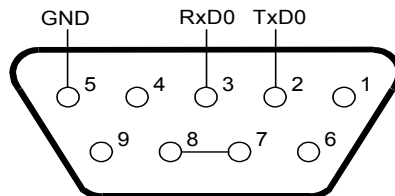
Name in schematic	Default configuration	Description
S102		Startup configuration: Standard start from internal Flash OFF-OFF-OFF-OFF
S102		Startup configuration: Bootstrap loader ASC ON-ON-OFF-OFF
S102		Startup configuration: Bootstrap loader CAN ON-OFF-ON-OFF
S102		Startup configuration Adapt Mode ON-ON-ON-OFF
S102		Startup configuration All other positions are reserved

Note: For debugging purpose (OCDS) the standard start from internal Flash configuration must be used.

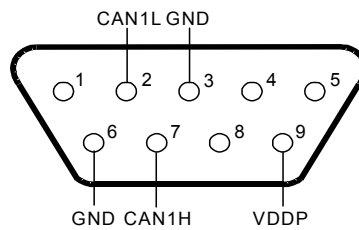
Description of Connectors and Switches

3.2 Headers and Connectors

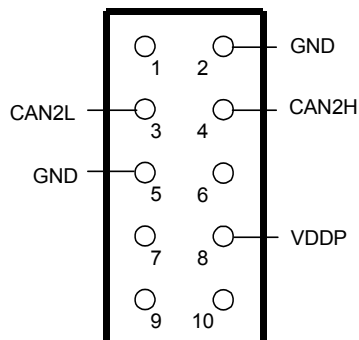
3.2.1 RS-232 Connector - ASC0 (P101)



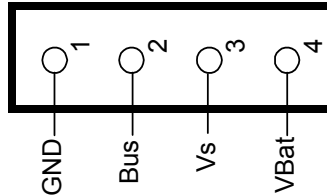
3.2.2 CAN1 (P102)



3.2.3 CAN2 (X103)

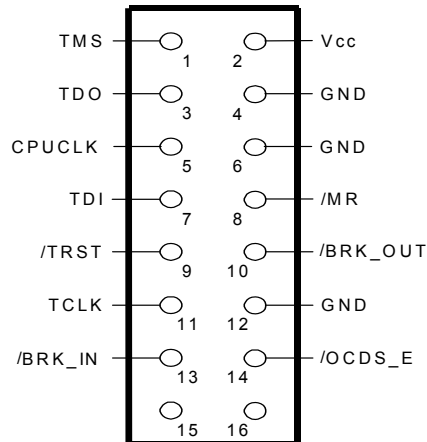


3.2.4 LIN Header (X104)



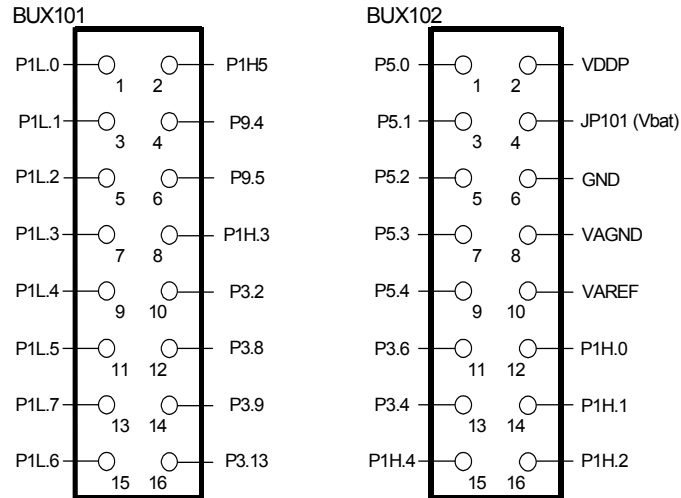
3.2.5 OCDS Interface

On-board header X501



3.2.6 Power Headers (optional)

The power headers can be mounted if a power inverter board for electrical motor drive application is used.



3.3 Pin Definition and Location

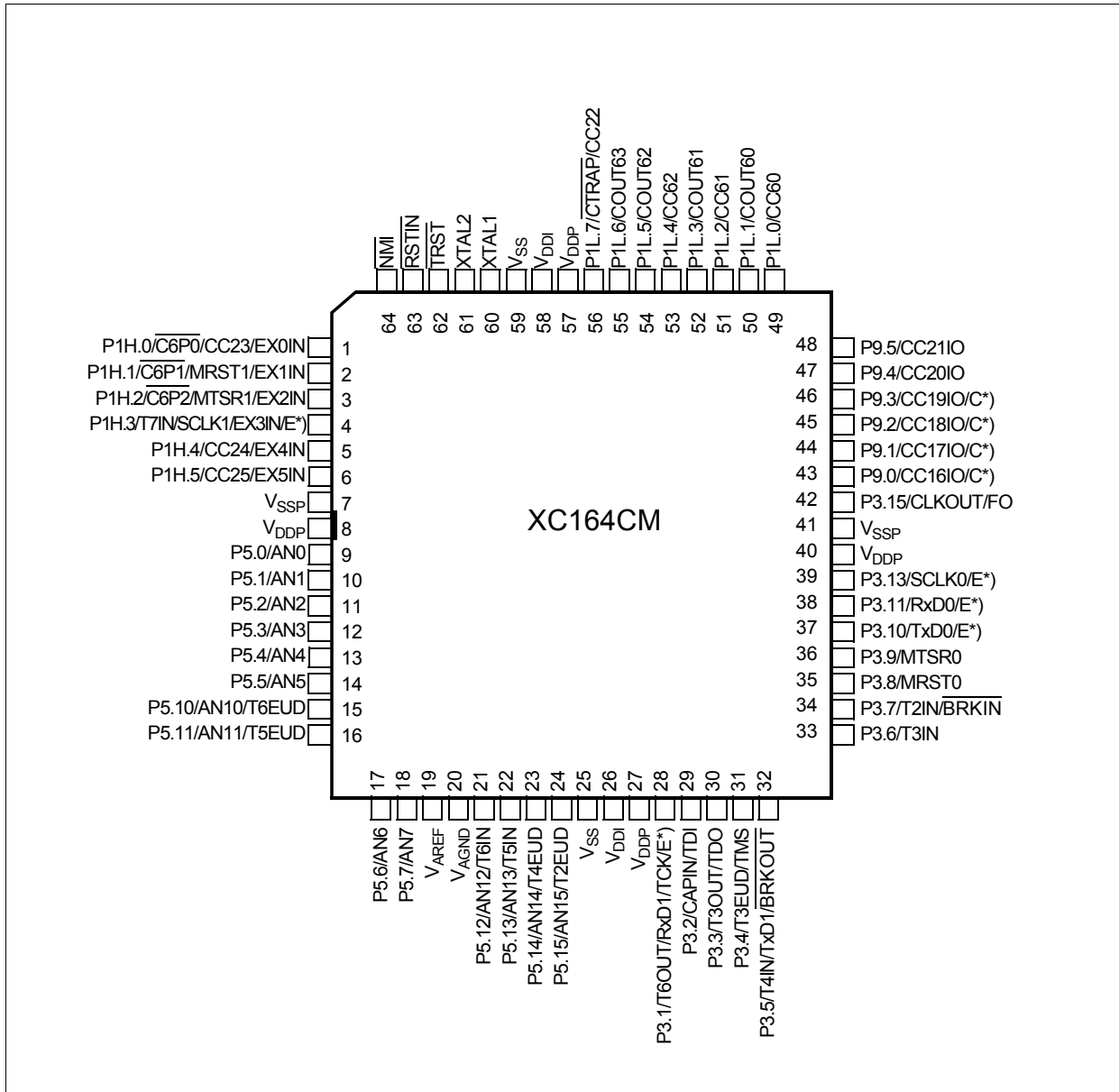


Figure 5 Pinout of the XC164CM

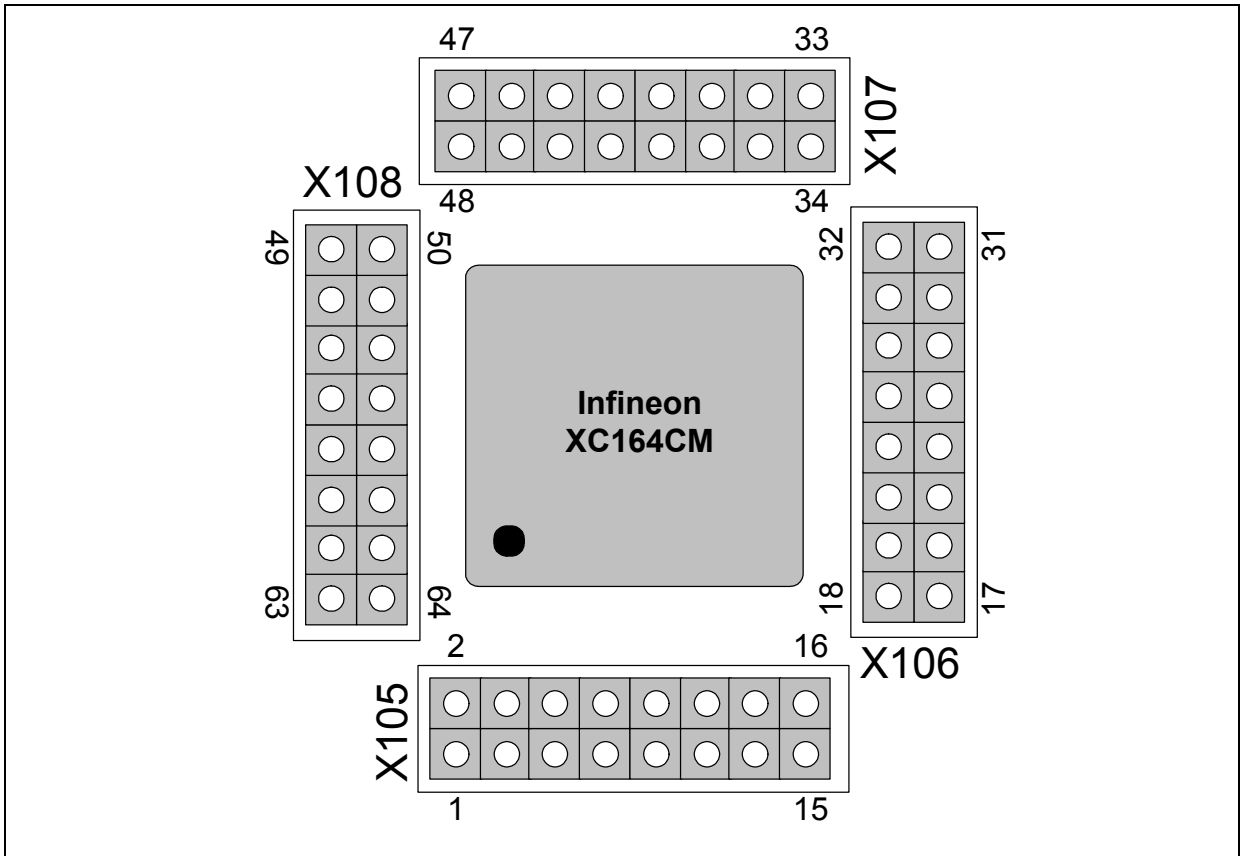


Figure 6 Pin connector of the XC164CM Easy Kit

Description of Connectors and Switches

3.4 Zero Ohm Resistors

For configuration purposes several zero ohm resistors have been implemented. The functionality of these resistors are shown in the table below.

Table 4 Zero Ohm Resistors

Component	Name in schematic	Description
TLE 6259-26 (LIN Transceiver Board Rev V2.0) TLE 7259 (LIN Transceiver Board Rev V2.1)	R123 R147 / R148	enable / disable connect / disconnect
TLE 6250G (CAN Transceiver)	R149 / R 150 R151 / R152 R128 R129 R143 R144 R124 / R130 R131 / R132	connect / disconnect (CAN1) connect / disconnect (CAN2) enable / disable (CAN1) enable / disable (CAN2) supply Bus voltage internal / external (CAN1) supply Bus voltage internal / external (CAN2) connect Bus / disconnect Bus (CAN1) connect Bus / disconnect Bus (CAN1)
TLE 7469V52 (Voltage Regulator)	R120 R121 R118 / R119 R116	disable / enable Watchdog input disable / enable Watchdog functionality connect / disconnect 5 V / 2.6V voltage disable / enable voltage regulator
HIN202IBN (RS232 Level Shifter)	R153 R154 R155	Connect / disconnect Transmit TxD0 Connect / disconnect Receive TxD0 On / off levelshifter device
Status LED's oscillator circuit Analog reference	R125 R122 R126 / R127	connect / disconnect LED's to 5 V oscillator gain change of analog reference source

4 Memory Models

The memory space of the XC164CM is configured in a “von Neumann” architecture. This means that code and data are accessed within the same linear address space.

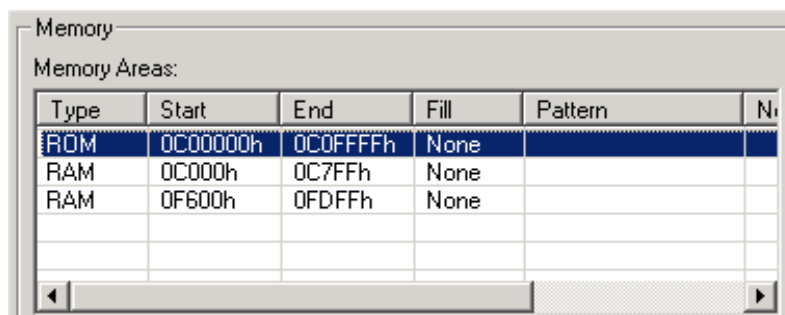
Attached there are two examples for memory mapping of the XC164CM Board.

4.1 Internal Flash

The XC164CM incorporates 64 Kbytes of embedded Flash memory (starting at location C0'0000H) for code or constant data. It is operated from the 5 V pad supply and requires no additional programming voltage. The Flash array is organized in five sectors of 4 × 8 Kbytes, and 1 × 32 Kbytes¹). It combines the advantages of very fast read accesses with protected but simple writing algorithms for programming and erasing. The 64-bit code read accesses realize maximum CPU performance by fetching two double word instructions (or four single word instructions) in a single access cycle.

Data integrity is enhanced by an error correction code enabling dynamic correction of single bit errors. Additionally, special margin checks are provided to detect and correct problematic bits before they lead to actual malfunctions.

The On-chip programming can be done either with a utility program, so called “Memtool” or with several other Toolchains of our Tool vendors. Memtool is using the ASC bootstrap Loader. The latest version can be found on the Infineon web side. Other tools are using the OCDS interface.

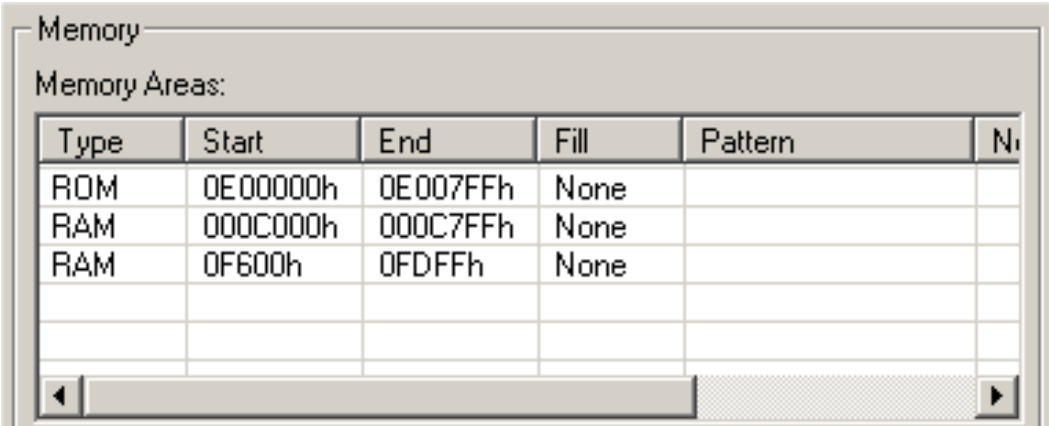


Type	Start	End	Fill	Pattern	Name
ROM	0C00000h	0C0FFFFh	None		
RAM	0C000h	0C7FFh	None		
RAM	0F600h	0FDFFh	None		

Figure 7 Example for memory mapping (internal flash)

4.2 Internal PRAM

The XC164CM provides 2 Kbytes of PSRAM (E0'0000H ... E0'07FFH). The PSRAM provides fast code execution without initial delays. Therefore, it supports non-sequential code execution, for example via the interrupt vector table.

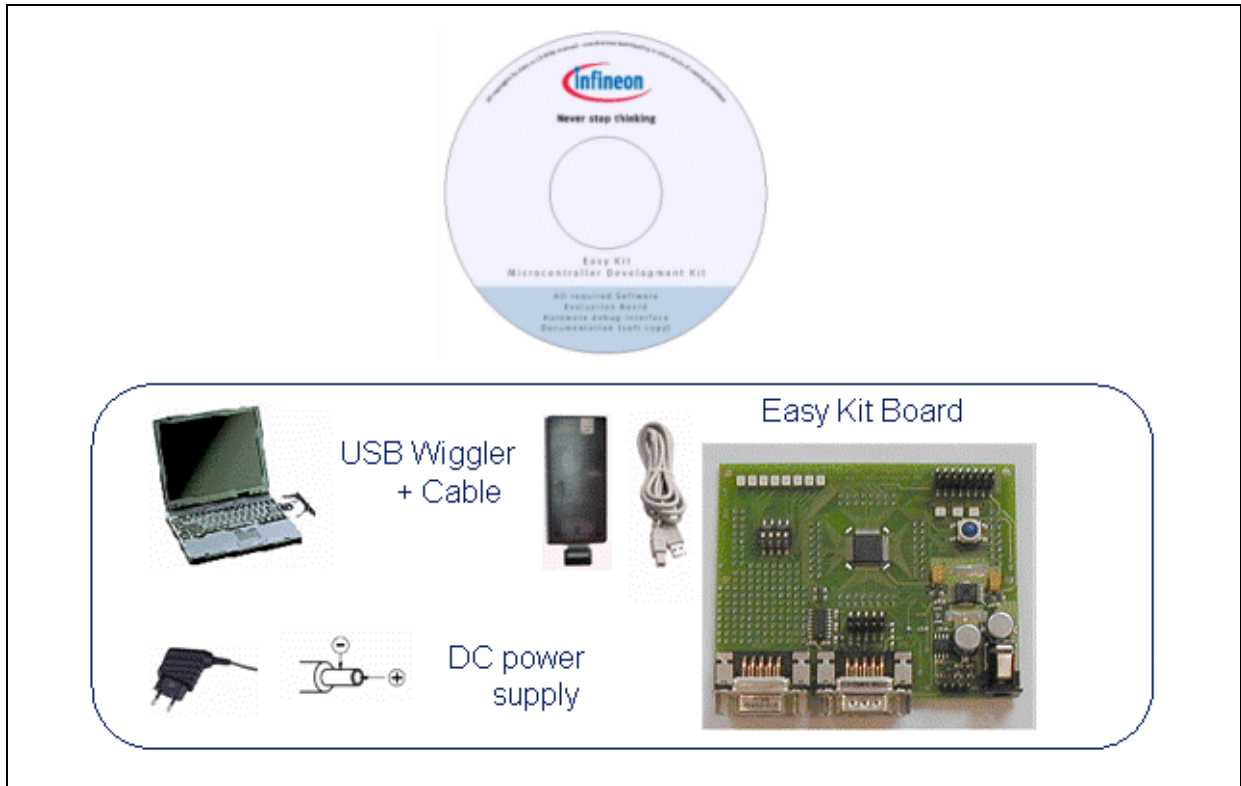


Type	Start	End	Fill	Pattern	Name
ROM	0E00000h	0E007FFh	None		
RAM	000C000h	000C7FFh	None		
RAM	0F600h	0FDFFh	None		

Figure 8 Memory mapping for internal PRAM

5 Quick Start Up

For a successful start up of the XC164CMEasy Kit the following items should be done:
Start the index.htm on the EasyKit CD and follow the Getting Started.



5.1 Power Supply

A regulated DC power supply with max. 12 Volts / 400mA should be connected to the power connector. Both green LED's should be active.

Please Note, the power supply is not part of the delivery !

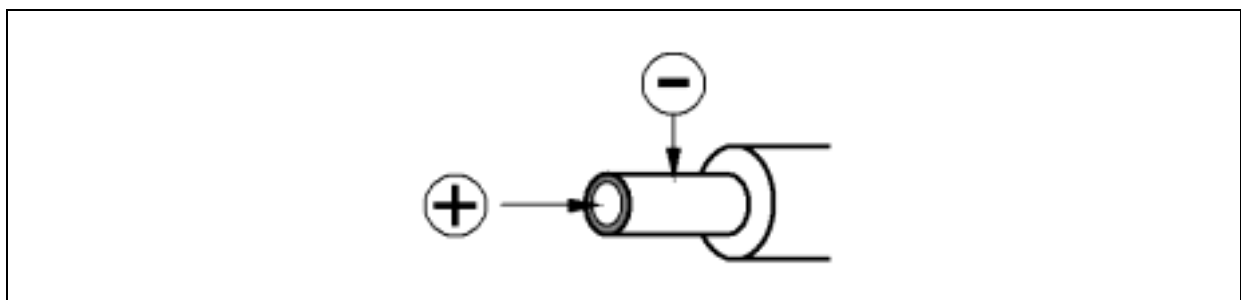


Figure 9 Power Supply Connector

5.2 OCDS debugging interface

The XC164CM includes an On-Chip Debug Support (OCDS) system, which provides convenient debugging, controlled directly by an external device via debug interface pins. Within the XC164CM Easy Kit you get the USB Wiggler. For installing all the required Hardware and Software please follow the Getting Started on the Easy Kit CD by click on the Logo.



Figure 10 Getting Started on Easy Kit CD

5.3 RS232 Interface

For flashing the program to the microcontroller a serial interface among the PC(RS232/COMx interface) and the XC164M board(ASC0/P101) is needed.

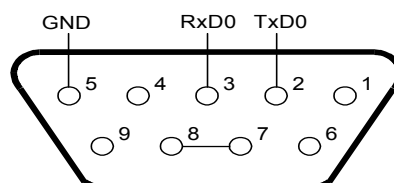


Figure 11 ASC0 Interface on the XC164CM board

5.4 MemTool

What is Memtool?

Memtool is one of Infineon's solutions for programming code and data into FLASH Memory. Memtool supports on-chip FLASH Memory as well as dedicated Flash chips on the target board.

Memtool uses the ASC bootstrap Loader and can be found on the XC164CM Starterkit CD under Tools.

5.5 ASC-Bootstrap

To establish the connection between the ASC bootstrap loader of the XC164CM microcontroller and the PC (MemTool) the bootstrap loader mode has to be configured.

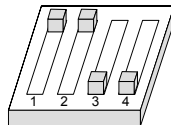


Figure 12 ASC Bootstrap loader mode (DIP Switch S102)

5.6 Start Memtool

Go to Target dialog (Target ? Change) and select 'Generic Target with 'SAB XC164CM-8FF' from the list. Select the Baud rate and Click 'ok'

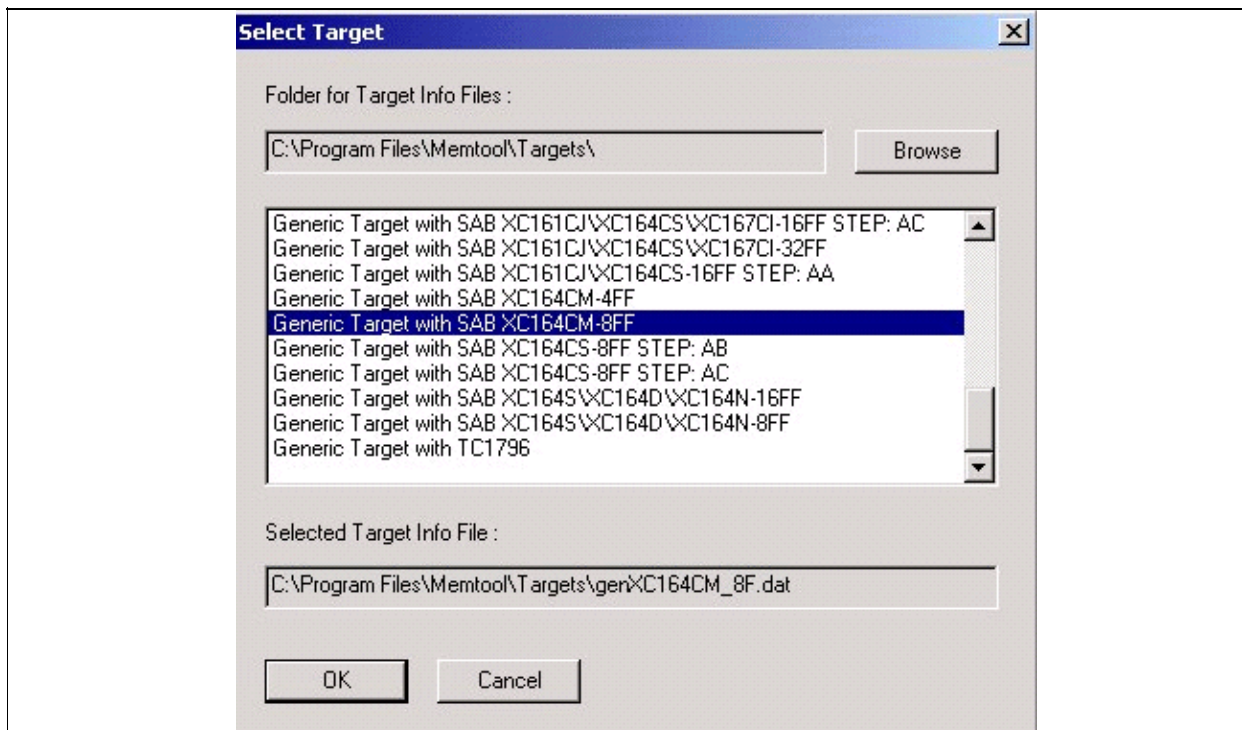


Figure 13 Configuration of the microcontroller type

5.7 Connect to the Target

Make sure that the Starter Kit board is connected to your PC as well as to your power supply. Hit the reset key on the starter kit. Now press the 'connect' button in Memtool.

If the software status bar displays 'Ready for Memtool Command' you successfully installed Memtool.

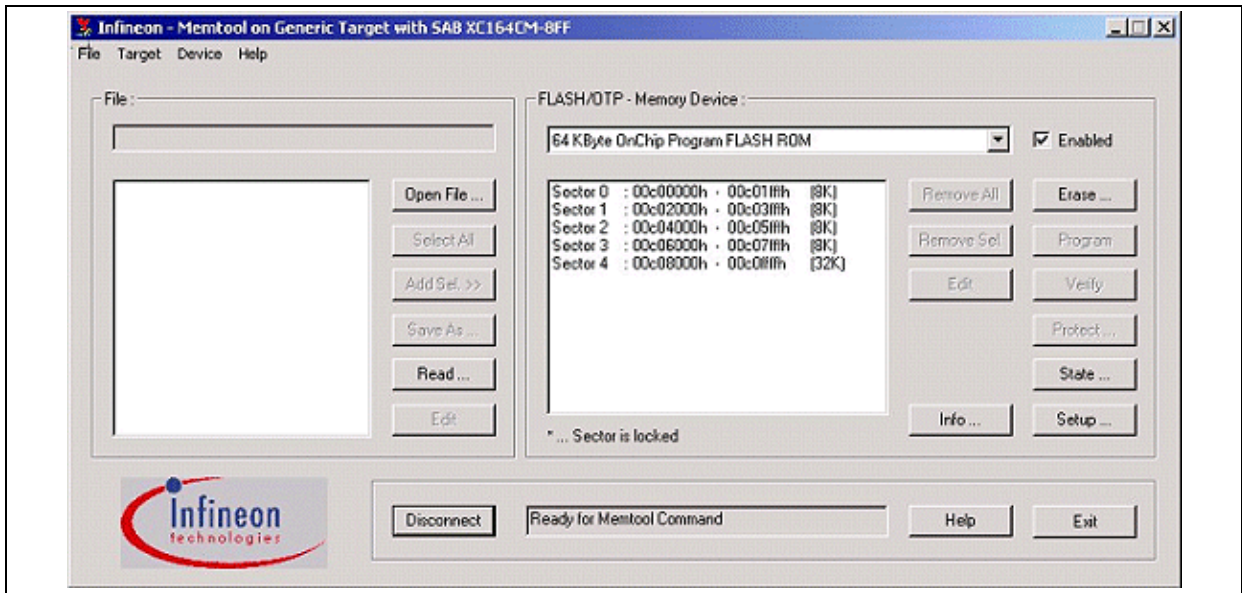


Figure 14 Successful connection

5.8 Prepare Memtool for programming

Check the setup for programming, select "Automatic Erase before Program" and Automatic Verify after Program

Open the compiled hex file (*.hex / *.h86) from the project directory and push the "Select All" and "Add Sel.>>" Buttons

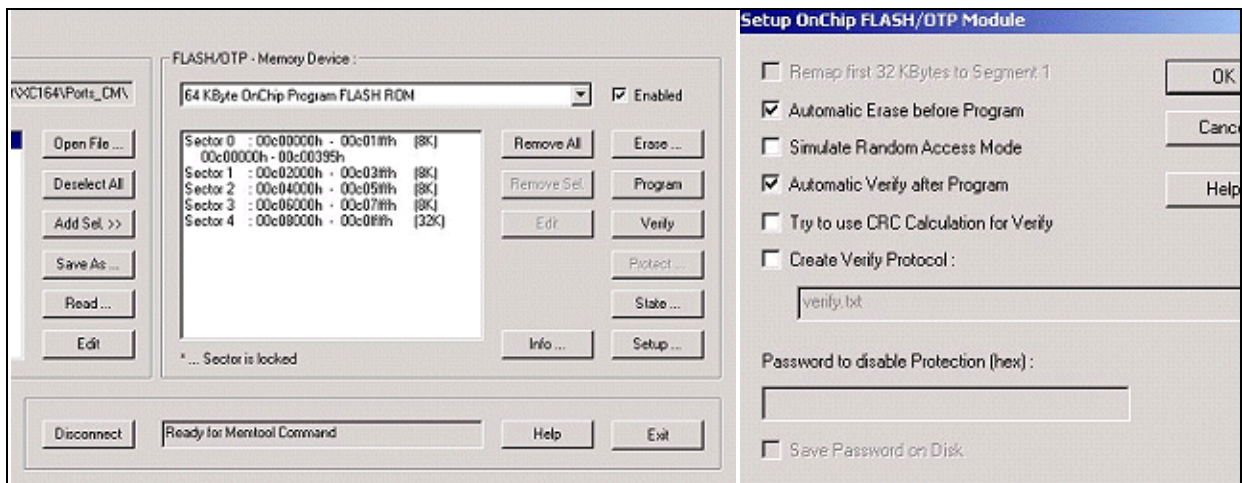


Figure 15 Setup for programming

5.9 Program

Press the “Program” Button and check the result of the programming.



Figure 16 Program

After the successful program press “Disconnect Now”

5.10 Execution Mode

After the code is programmed in the internal flash the microcontroller has to be configured in the standard start mode.

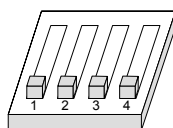


Figure 17 Standard start mode (DIP Switch S102)

After the reset button(blue) is pressed the program is executed from the internal flash.



Edition V 1.0

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“Business excellence means intelligent approaches and clearly defined processes, which are both constantly under review and ultimately lead to good operating results.

Better operating results and business excellence mean less idleness and wastefulness for all of us, more professional success, more accurate information, a better overview and, thereby, less frustration and more satisfaction.”

<http://>