

# 250mA/60MHz Current Feedback Amplifier

## FEATURES

- 250mA Minimum Output Drive Current
- 60MHz Bandwidth,  $A_V = 2$ ,  $R_I = 100\Omega$
- 900V/ $\mu$ s Slew Rate, A<sub>V</sub> = 2,  $R_L = 50\Omega$
- 0.02% Differential Gain,  $A_V = 2$ ,  $R_L = 30\Omega$
- 0.17° Differential Phase,  $A_V = 2$ ,  $R_I = 30\Omega$
- High Input Impedance, 10MΩ
- Wide Supply Range, ±5V to ±15V
- Shutdown Mode: I<sub>S</sub> < 200μA</li>
- Adjustable Supply Current
- Stable with C<sub>L</sub> = 10,000pF

## **APPLICATIONS**

- Video Amplifiers
- Cable Drivers
- RGB Amplifiers
- Test Equipment Amplifiers
- Buffers

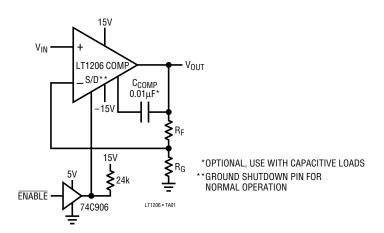
## DESCRIPTION

The LT1206 is a current feedback amplifier with high output current drive capability and excellent video characteristics. The LT1206 is stable with large capacitive loads, and can easily supply the large currents required by the capacitive loading. A shutdown feature switches the device into a high impedance, low current mode, reducing dissipation when the device is not in use. For lower bandwidth applications, the supply current can be reduced with a single external resistor. The low differential gain and phase, wide bandwidth, and the 250mA minimum output current drive make the LT1206 well suited to drive multiple cables in video systems.

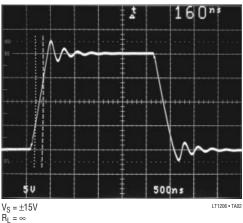
The LT1206 is manufactured on Linear Technology's proprietary complementary bipolar process.

# TYPICAL APPLICATIONS

## Noninverting Amplifier with Shutdown



Large-Signal Response,  $C_L = 10,000pF$ 



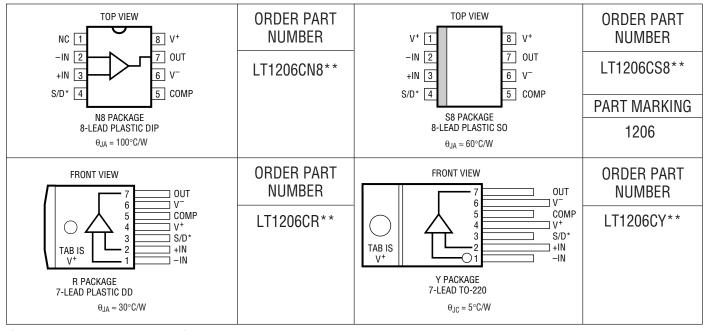
 $R_E = R_G = 3k$ 

## **ABSOLUTE MAXIMUM RATINGS**

Supply Voltage	±18V
Input Current	±15mA
Output Short-Circuit Duration (Note 1)	Continuous
Specified Temperature Range (Note 2)	0°C to 70°C

Operating Temperature Range	
LT1206C	40°C to 85°C
Junction Temperature	150°C
Storage Temperature Range	–65°C to 150°C
Lead Temperature (Soldering, 10 sec	) 300°C

## PACKAGE/ORDER INFORMATION



<sup>\*</sup>Ground shutdown pin for normal operation \*\*\*

#### \*\*See Note 2

# **ELECTRICAL CHARACTERISTICS** $V_{CM}$ = 0, $\pm 5V \le V_S \le \pm 15V$ , pulse tested, $V_{S/D}$ = 0V, unless otherwise noted.

SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
V <sub>0S</sub>	Input Offset Voltage	T <sub>A</sub> = 25°C	•		±3	±10 ±15	mV mV
	Input Offset Voltage Drift		•		10		μV/°C
I <sub>IN</sub> <sup>+</sup>	Noninverting Input Current	T <sub>A</sub> = 25°C	•		±2	±8 ±25	μA μA
I <sub>IN</sub> -	Inverting Input Current	T <sub>A</sub> = 25°C	•		±10	±60 ±100	μA μA
e <sub>n</sub>	Input Noise Voltage Density	$f = 10kHz$ , $R_F = 1k$ , $R_G = 10\Omega$ , $R_S = 0\Omega$			3.6		nV/√Hz
+i <sub>n</sub>	Input Noise Current Density	$f = 10kHz, R_F = 1k, R_G = 10\Omega, R_S = 10k$			2		pA/√Hz
-i <sub>n</sub>	Input Noise Current Density	$f = 10kHz$ , $R_F = 1k$ , $R_G = 10Ω$ , $R_S = 10k$			30		pA/√Hz
R <sub>IN</sub>	Input Resistance	$V_{IN} = \pm 12V, V_S = \pm 15V$ $V_{IN} = \pm 2V, V_S = \pm 5V$	•	1.5 0.5	10 5		MΩ MΩ
C <sub>IN</sub>	Input Capacitance	$V_S = \pm 15V$			2		pF
	Input Voltage Range	$V_S = \pm 15V$ $V_S = \pm 5V$	•	±12 ±2	±13.5 ±3.5		V V

# **ELECTRICAL CHARACTERISTICS** $V_{CM}$ = 0, $\pm 5V \le V_S \le \pm 15V$ , pulse tested, $V_{S/D}$ = 0V, unless otherwise noted.

SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
CMRR	Common-Mode Rejection Ratio	$V_S = \pm 15V, V_{CM} = \pm 12V$ $V_S = \pm 5V, V_{CM} = \pm 2V$	•	55 50	62 60		dB dB
	Inverting Input Current Common-Mode Rejection	$V_S = \pm 15V, V_{CM} = \pm 12V$ $V_S = \pm 5V, V_{CM} = \pm 2V$	•		0.1 0.1	10 10	μΑ/V μΑ/V
PSRR	Power Supply Rejection Ratio	$V_{S} = \pm 5V \text{ to } \pm 15V$	•	60	77		dB
	Noninverting Input Current Power Supply Rejection	$V_S = \pm 5V \text{ to } \pm 15V$	•		30	500	nA/V
	Inverting Input Current Power Supply Rejection	$V_S = \pm 5V \text{ to } \pm 15V$	•		0.7	5	μA/V
A <sub>V</sub>	Large-Signal Voltage Gain	$V_S = \pm 15V$ , $V_{OUT} = \pm 10V$ , $R_L = 50\Omega$ $V_S = \pm 5V$ , $V_{OUT} = \pm 2V$ , $R_L = 25\Omega$	•	55 55	71 68		dB dB
R <sub>OL</sub>	Transresistance, ΔV <sub>OUT</sub> /ΔI <sub>IN</sub> <sup>-</sup>	$V_S = \pm 15V$ , $V_{OUT} = \pm 10V$ , $R_L = 50\Omega$ $V_S = \pm 5V$ , $V_{OUT} = \pm 2V$ , $R_L = 25\Omega$	•	100 75	260 200		kΩ kΩ
V <sub>OUT</sub>	Maximum Output Voltage Swing	$V_S = \pm 15V$ , $R_L = 50\Omega$ , $T_A = 25^{\circ}C$	•	±11.5 ±10.0	±12.5		V
	$V_S = \pm 5V, R_L = 25\Omega, T_A = 25^{\circ}C$	•	±2.5 ±2.0	±3.0		V	
I <sub>OUT</sub>	Maximum Output Current	$R_L = 1\Omega$	•	250	500	1200	mA
I <sub>S</sub>	Supply Current	$V_S = \pm 15V$ , $V_{S/D} = 0V$ , $T_A = 25$ °C	•		20	30 35	mA mA
	Supply Current, R <sub>S/D</sub> = 51k (Note 3)	$V_S = \pm 15V, T_A = 25^{\circ}C$			12	17	mA
	Positive Supply Current, Shutdown	$V_S = \pm 15V, V_{S/D} = 15V$	•			200	μΑ
	Output Leakage Current, Shutdown	$V_S = \pm 15V, V_{S/D} = 15V$	•			10	μΑ
SR	Slew Rate (Note 4)	$A_V = 2, T_A = 25^{\circ}C$		400	900		V/µs
	Differential Gain (Note 5)	$V_S=\pm 15V,~R_F=560\Omega,~R_G=560\Omega,~R_L=30\Omega$			0.02		%
	Differential Phase (Note 5)	$V_S=\pm 15V,~R_F=560\Omega,~R_G=560\Omega,~R_L=30\Omega$			0.17		DEG
BW	Small-Signal Bandwidth	$V_S = \pm 15V$ , Peaking $\leq 0.5 dB$ $R_F = R_G = 620\Omega$ , $R_L = 100\Omega$			60		MHz
		$V_S = \pm 15V$ , Peaking $\leq 0.5 dB$ $R_F = R_G = 649\Omega$ , $R_L = 50\Omega$			52		MHz
		$V_S = \pm 15V$ , Peaking $\leq 0.5 dB$ $R_F = R_G = 698\Omega$ , $R_L = 30\Omega$			43		MHz
		$V_S = \pm 15V$ , Peaking $\leq 0.5 dB$ $R_F = R_G = 825\Omega$ , $R_L = 10\Omega$			27		MHz

The ullet denotes specifications which apply for  $0^{\circ}C \leq T_A \leq 70^{\circ}C$ .

**Note 1:** Applies to short circuits to ground only. A short circuit between the output and either supply may permanently damage the part when operated on supplies greater than  $\pm 10V$ .

**Note 2:** Commercial grade parts are designed to operate over the temperature range of  $-40^{\circ}\text{C}$  to 85°C but are neither tested nor guaranteed

beyond 0°C to 70°C. Industrial grade parts tested over  $-40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$  are available on special request. Consult factory.

Note 3:  $R_{S/D}$  is connected between the shutdown pin and ground.

**Note 4:** Slew rate is measured at  $\pm 5V$  on a  $\pm 10V$  output signal while operating on  $\pm 15V$  supplies with  $R_F=1.5k$ ,  $R_G=1.5k$  and  $R_L=400\Omega$ .

Note 5: NTSC composite video with an output level of 2V.



# **SMALL-SIGNAL BANDWIDTH**

## $I_S$ = 20mA Typical, Peaking $\leq$ 0.1dB

A <sub>V</sub>	R <sub>L</sub>	R <sub>F</sub>	R <sub>G</sub>	-3dB BW (MHz)	-0.1dB BW (MHz)		
$V_S = \pm 5V$ , $R_{SD} = 0\Omega$							
-1	150	562	562	48	21.4		
	30	649	649	34	17		
	10	732	732	22	12.5		
1	150	619	-	54	22.3		
	30	715	-	36	17.5		
	10	806	-	22.4	11.5		
2	150	576	576	48	20.7		
	30	649	649	35	18.1		
	10	750	750	22.4	11.7		
10	150	442	48.7	40	19.2		
	30	511	56.2	31	16.5		
	10	649	71.5	20	10.2		

Av	RL	R <sub>F</sub>	R <sub>G</sub>	-3dB BW (MHz)	-0.1dB BW (MHz)
V <sub>S</sub> = ±15	V, R <sub>SD</sub> = (	Ω			
-1	150	681	681	50	19.2
	30	768	768	35	17
	10	887	887	24	12.3
1	150	768	-	66	22.4
	30	909	-	37	17.5
	10	1k	-	23	12
2	150	665	665	55	23
	30	787	787	36	18.5
	10	931	931	22.5	11.8
10	150	487	536	44	20.7
	30	590	64.9	33	17.5
	10	768	84.5	20.7	10.8

## $I_S$ = 10mA Typical, Peaking $\leq$ 0.1dB

A <sub>V</sub>	RL	R <sub>F</sub>	R <sub>G</sub>	-3dB BW (MHz)	-0.1dB BW (MHz)		
$V_S = \pm 5V, R_{SD} = 10.2k$							
-1	150	576	576	35	17		
	30	681	681	25	12.5		
	10	750	750	16.4	8.7		
1	150	665	-	37	17.5		
	30	768	-	25	12.6		
	10	845	-	16.5	8.2		
2	150	590	590	35	16.8		
	30	681	681	25	13.4		
	10	768	768	16.2	8.1		
10	150	301	33.2	31	15.6		
	30	392	43.2	23	11.9		
	10	499	54.9	15	7.8		

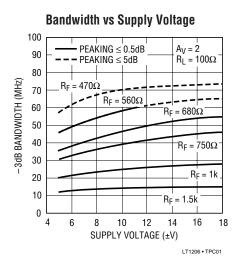
A <sub>V</sub>	RL	R <sub>F</sub>	R <sub>G</sub>	-3dB BW (MHz)	-0.1dB BW (MHz)			
V <sub>S</sub> = ±15	$V_S = \pm 15V$ , $R_{SD} = 60.4k$							
-1	150	634	634	41	19.1			
	30	768	768	26.5	14			
	10	866	866	17	9.4			
1	150	768	-	44	18.8			
	30	909	-	28	14.4			
	10	1k	-	16.8	8.3			
2	150	649	649	40	18.5			
	30	787	787	27	14.1			
	10	931	931	16.5	8.1			
10	150	301	33.2	33	15.6			
	30	402	44.2	25	13.3			
	10	590	64.9	15.3	7.4			

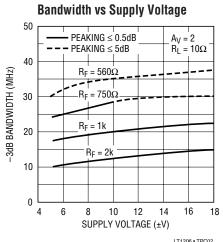
## $I_S = 5mA$ Typical, Peaking $\leq 0.1dB$

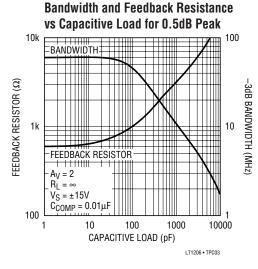
•	,,		•				
A <sub>V</sub>	RL	R <sub>F</sub>	R <sub>G</sub>	-3dB BW (MHz)	-0.1dB BW (MHz)		
$V_S = \pm 5V$ , $R_{SD} = 22.1k$							
-1	150	604	604	21	10.5		
	30	715	715	14.6	7.4		
	10	681	681	10.5	6.0		
1	150	768	-	20	9.6		
	30	866	-	14.1	6.7		
	10	825	-	9.8	5.1		
2	150	634	634	20	9.6		
	30	750	750	14.1	7.2		
	10	732	732	9.6	5.1		
10	150	100	11.1	16.2	5.8		
	30	100	11.1	13.4	7.0		
	10	100	11.1	9.5	4.7		

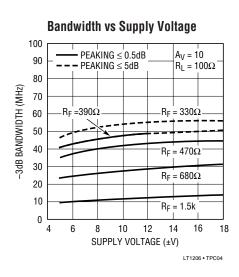
A <sub>V</sub>	RL	R <sub>F</sub>	R <sub>G</sub>	-3dB BW (MHz)	-0.1dB BW (MHz)
V <sub>S</sub> = ±15	V, R <sub>SD</sub> = 1	121k			
-1	150	619	619	25	12.5
	30	787	787	15.8	8.5
	10	825	825	10.5	5.4
1	150	845	_	23	10.6
	30	1k	_	15.3	7.6
	10	1k	_	10	5.2
2	150	681	681	23	10.2
	30	845	845	15	7.7
	10	866	866	10	5.4
10	150	100	11.1	15.9	4.5
	30	100	11.1	13.6	6
	10	100	11.1	9.6	4.5

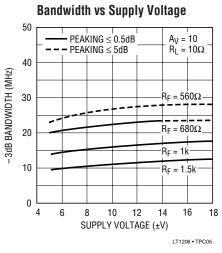
## TYPICAL PERFORMANCE CHARACTERISTICS

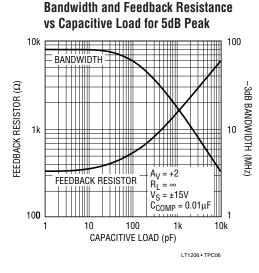


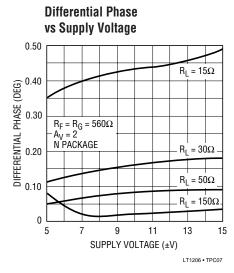


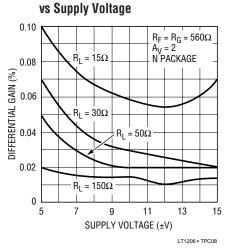




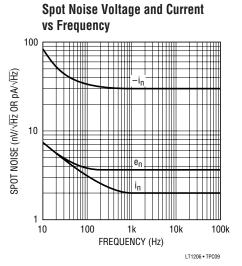




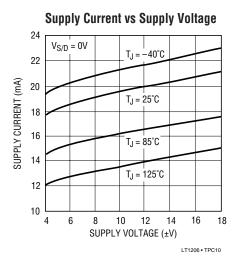


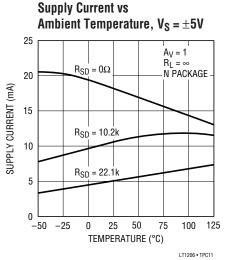


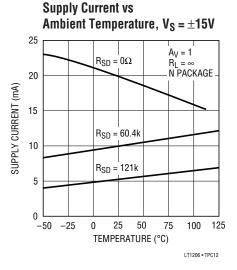
**Differential Gain** 

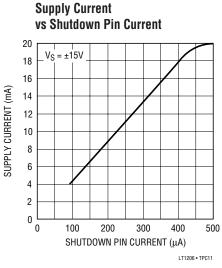


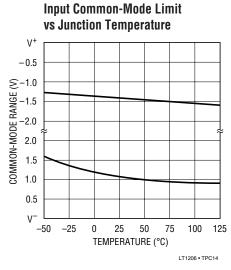
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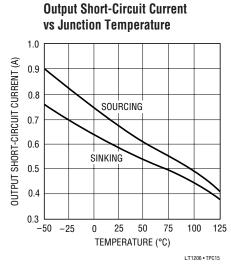


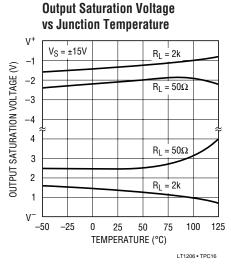


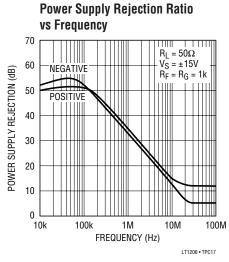


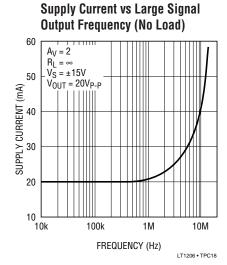






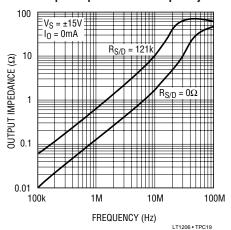




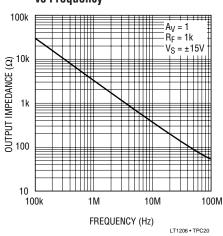


# TYPICAL PERFORMANCE CHARACTERISTICS

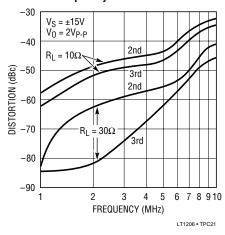
#### **Output Impedance vs Frequency**



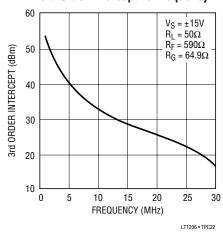
# Output Impedance in Shutdown vs Frequency



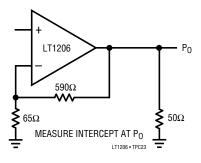
# 2nd and 3rd Harmonic Distortion vs Frequency



#### 3rd Order Intercept vs Frequency

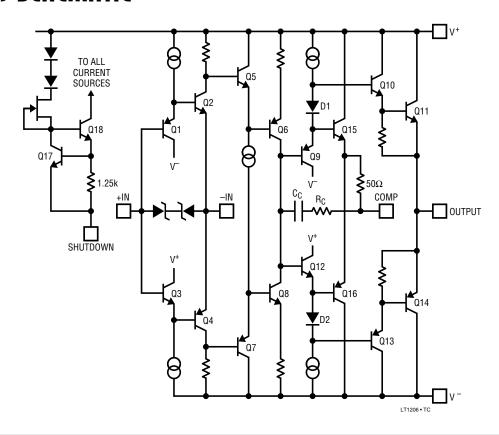


### **Test Circuit for 3rd Order Intercept**





## SIMPLIFIED SCHEMATIC



# APPLICATIONS INFORMATION

The LT1206 is a current feedback amplifier with high output current drive capability. The device is stable with large capacitive loads and can easily supply the high currents required by capacitive loads. The amplifier will drive low impedance loads such as cables with excellent linearity at high frequencies.

### **Feedback Resistor Selection**

The optimum value for the feedback resistors is a function of the operating conditions of the device, the load impedance and the desired flatness of response. The Typical AC Performance tables give the values which result in the highest 0.1dB and 0.5dB bandwidths for various resistive loads and operating conditions. If this level of flatness is not required, a higher bandwidth can be obtained by use of a lower feedback resistor. The characteristic curves of Bandwidth vs Supply Voltage indicate feedback resistors for peaking up to 5dB. These curves use a solid line when the response has less than 0.5dB of peaking and a dashed

line when the response has 0.5dB to 5dB of peaking. The curves stop where the response has more than 5dB of peaking.

For resistive loads, the COMP pin should be left open (see section on capacitive loads).

## **Capacitive Loads**

The LT1206 includes an optional compensation network for driving capacitive loads. This network eliminates most of the output stage peaking associated with capacitive loads, allowing the frequency response to be flattened. Figure 1 shows the effect of the network on a 200pF load. Without the optional compensation, there is a 5dB peak at 40MHz caused by the effect of the capacitance on the output stage. Adding a 0.01µF bypass capacitor between the output and the COMP pins connects the compensation and completely eliminates the peaking. A lower value feedback resistor can now be used, resulting in a response



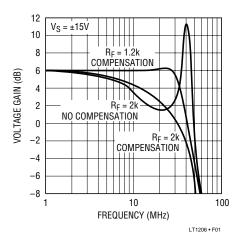


Figure 1.

which is flat to 0.35dB to 30MHz. The network has the greatest effect for  $C_L$  in the range of 0pF to 1000pF. The graph of Maximum Capacitive Load vs Feedback Resistor can be used to select the appropriate value of feedback resistor. The values shown are for 0.5dB and 5dB peaking at a gain of 2 with no resistive load. This is a worst case condition, as the amplifier is more stable at higher gains and with some resistive load in parallel with the capacitance. Also shown is the -3dB bandwidth with the suggested feedback resistor vs the load capacitance.

Although the optional compensation works well with capacitive loads, it simply reduces the bandwidth when it is connected with resistive loads. For instance, with a  $30\Omega$  load, the bandwidth drops from 55MHz to 35MHz when the compensation is connected. Hence, the compensation was made optional. To disconnect the optional compensation, leave the COMP pin open.

#### Shutdown/Current Set

# If the shutdown feature is not used, the SHUTDOWN pin must be connected to ground or $V^-$ .

The shutdown pin can be used to either turn off the biasing for the amplifier, reducing the quiescent current to less than  $200\mu A$ , or to control the quiescent current in normal operation.

The total bias current in the LT1206 is controlled by the current flowing out of the shutdown pin. When the shutdown pin is open or driven to the positive supply, the part is shut down. In the shutdown mode, the output looks like

a 40pF capacitor and the supply current is typically  $100\mu A$ . The shutdown pin is referenced to the positive supply through an internal bias circuit (see the simplified schematic). An easy way to force shutdown is to use open drain (collector) logic. The circuit shown in Figure 2 uses a 74C904 buffer to interface between 5V logic and the LT1206. The switching time between the active and shutdown states is less than  $1\mu s$ . A 24k pull-up resistor speeds up the turn-off time and insures that the LT1206 is completely turned off. Because the pin is referenced to the positive supply, the logic used should have a breakdown voltage of greater than the positive supply voltage. No other circuitry is necessary as the internal circuit limits the shutdown pin current to about  $500\mu A$ . Figure 3 shows the resulting waveforms.

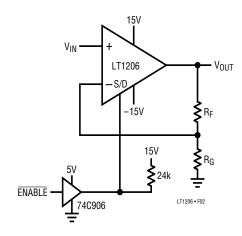


Figure 2. Shutdown Interface

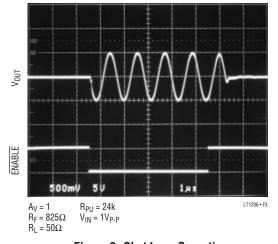


Figure 3. Shutdown Operation



For applications where the full bandwidth of the amplifier is not required, the quiescent current of the device may be reduced by connecting a resistor from the shutdown pin to ground. The quiescent current will be approximately 40 times the current in the shutdown pin. The voltage across the resistor in this condition is  $V^+ - 3V_{BE}$ . For example, a 60k resistor will set the quiescent supply current to 10mA with  $V_S = \pm 15V$ .

The photos (Figures 4a and 4b) show the effect of reducing the quiescent supply current on the large-signal response. The quiescent current can be reduced to 5mA in the inverting configuration without much change in response. In noninverting mode, however, the slew rate is reduced as the quiescent current is reduced.

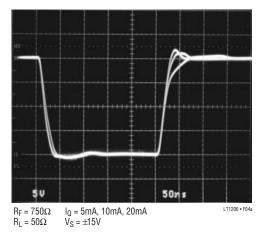


Figure 4a. Large-Signal Response vs  $I_0$ ,  $A_V = -1$ 

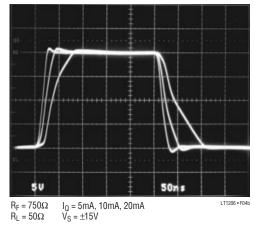


Figure 4b. Large-Signal Response vs  $I_0$ ,  $A_V = 2$ 

#### **Slew Rate**

Unlike a traditional op amp, the slew rate of a current feedback amplifier is not independent of the amplifier gain configuration. There are slew rate limitations in both the input stage and the output stage. In the inverting mode, and for higher gains in the noninverting mode, the signal amplitude on the input pins is small and the overall slew rate is that of the output stage. The input stage slew rate is related to the quiescent current and will be reduced as the supply current is reduced. The output slew rate is set by the value of the feedback resistors and the internal capacitance. Larger feedback resistors will reduce the slew rate as will lower supply voltages, similar to the way the bandwidth is reduced. The photos (Figures 5a, 5b and 5c) show the large-signal response of the LT1206 for various gain configurations. The slew rate varies from 860V/ $\mu$ s for a gain of 1, to 1400V/ $\mu$ s for a gain of -1.

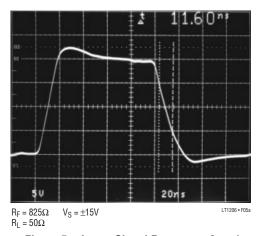


Figure 5a. Large-Signal Response,  $A_V = 1$ 

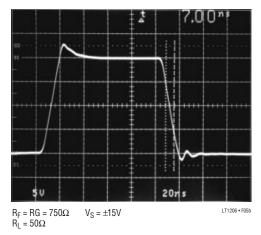


Figure 5b. Large-Signal Response,  $A_V = -1$ 

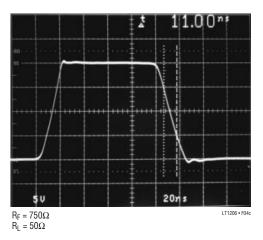


Figure 5c. Large-Signal Response,  $A_V = 2$ 

When the LT1206 is used to drive capacitive loads, the available output current can limit the overall slew rate. In the fastest configuration, the LT1206 is capable of a slew rate of over 1V/ns. The current required to slew a capacitor at this rate is 1mA per picofarad of capacitance, so 10,000pF would require 10A! The photo (Figure 6) shows the large signal behavior with  $C_L = 10,000$ pF. The slew rate is about  $60V/\mu s$ , determined by the current limit of 600mA.

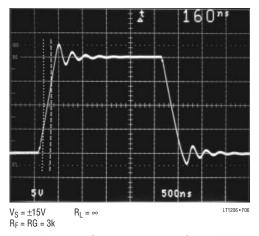


Figure 6. Large-Signal Response,  $C_1 = 10,000pF$ 

## **Differential Input Signal Swing**

The differential input swing is limited to about  $\pm 6V$  by an ESD protection device connected between the inputs. In normal operation, the differential voltage between the input pins is small, so this clamp has no effect; however, in the shutdown mode the differential swing can be the same as the input swing. The clamp voltage will then set

the maximum allowable input voltage. To allow for some margin, it is recommended that the input signal be less than  $\pm 5V$  when the device is shut down.

### Capacitance on the Inverting Input

Current feedback amplifiers require resistive feedback from the output to the inverting input for stable operation. Take care to minimize the stray capacitance between the output and the inverting input. Capacitance on the inverting input to ground will cause peaking in the frequency response (and overshoot in the transient response), but it does not degrade the stability of the amplifier.

### **Power Supplies**

The LT1206 will operate from single or split supplies from  $\pm 5 \text{V}$  (10V total) to  $\pm 15 \text{V}$  (30V total). It is not necessary to use equal value split supplies, however the offset voltage and inverting input bias current will change. The offset voltage changes about  $500\mu\text{V}$  per volt of supply mismatch. The inverting bias current can change as much as  $5\mu\text{A}$  per volt of supply mismatch, though typically the change is less than  $0.5\mu\text{A}$  per volt.

#### **Thermal Considerations**

The LT1206 contains a thermal shutdown feature which protects against excessive internal (junction) temperature. If the junction temperature of the device exceeds the protection threshold, the device will begin cycling between normal operation and an off state. The cycling is not harmful to the part. The thermal cycling occurs at a slow rate, typically 10ms to several seconds, which depends on the power dissipation and the thermal time constants of the package and heat sinking. Raising the ambient temperature until the device begins thermal shutdown gives a good indication of how much margin there is in the thermal design.

For surface mount devices heat sinking is accomplished by using the heat spreading capabilities of the PC board and its copper traces. Experiments have shown that the heat spreading copper layer does not need to be electrically connected to the tab of the device. The PCB material can be very effective at transmitting heat between the pad area attached to the tab of the device, and a ground or



power plane layer either inside or on the opposite side of the board. Although the actual thermal resistance of the PCB material is high, the length/area ratio of the thermal resistance between the layer is small. Copper board stiffeners and plated through holes can also be used to spread the heat generated by the device.

Tables 1 and 2 list thermal resistance for each package. For the TO-220 package, thermal resistance is given for junction-to-case only since this package is usually mounted to a heat sink. Measured values of thermal resistance for several different board sizes and copper areas are listed for each surface mount package. All measurements were taken in still air on 3/32" FR-4 board with 1oz copper. This data can be used as a rough guideline in estimating thermal resistance. The thermal resistance for each application will be affected by thermal interactions with other components as well as board size and shape.

Table 1. R Package, 7-Lead DD

COPPER AREA			THERMAL RESISTANCE
TOPSIDE*	BACKSIDE	BOARD AREA	(JUNCTION-TO-AMBIENT)
2500 sq. mm	2500 sq. mm	2500 sq. mm	25°C/W
1000 sq. mm	2500 sq. mm	2500 sq. mm	27°C/W
125 sq. mm	2500 sq. mm	2500 sq. mm	35°C/W

<sup>\*</sup>Tab of device attached to topside copper

Table 2. S8 Package, 8-Lead Plastic SOIC

COPPER AREA			THERMAL RESISTANCE
TOPSIDE*	BACKSIDE	BOARD AREA	(JUNCTION-TO-AMBIENT)
2500 sq. mm	2500 sq. mm	2500 sq. mm	60°C/W
1000 sq. mm	2500 sq. mm	2500 sq. mm	62°C/W
225 sq. mm	2500 sq. mm	2500 sq. mm	65°C/W
100 sq. mm	2500 sq. mm	2500 sq. mm	69°C/W
100 sq. mm	1000 sq. mm	2500 sq. mm	73°C/W
100 sq. mm	225 sq. mm	2500 sq. mm	80°C/W
100 sq. mm	100 sq. mm	2500 sq. mm	83°C/W

<sup>\*</sup>Pins 1 and 8 attached to topside copper

#### Y Package, 7-Lead TO-220

Thermal Resistance (Junction-to-Case) = 5°C/W

#### N8 Package, 8-Lead DIP

Thermal Resistance (Junction-to-Ambient) = 100°C/W

### **Calculating Junction Temperature**

The junction temperature can be calculated from the equation:

$$T_{J} = (P_D \times \theta_{JA}) + T_A$$

where:

 $T_{,l}$  = Junction Temperature

T<sub>A</sub> = Ambient Temperature

P<sub>D</sub> = Device Dissipation

 $\theta_{\text{JA}}$  = Thermal Resistance (Junction-to Ambient)

As an example, calculate the junction temperature for the circuit in Figure 7 for the N8, S8, and R packages assuming a  $70^{\circ}$ C ambient temperature.

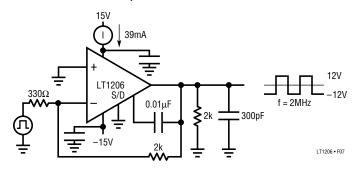


Figure 7. Thermal Calculation Example

The device dissipation can be found by measuring the supply currents, calculating the total dissipation, and then subtracting the dissipation in the load and feedback network.

$$P_D = (39\text{mA} \times 30\text{V}) - (12\text{V})^2/(2\text{k}||2\text{k}) = 1.03\text{W}$$

Then:

$$T_J = (1.03W \times 100^{\circ}C/W) + 70^{\circ}C = 173^{\circ}C$$
 for the N8 package

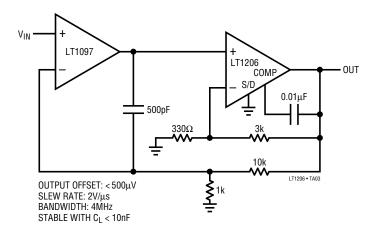
$$T_J = (1.03W \times 65^{\circ}C/W) \times + 70^{\circ}C = 137^{\circ}C$$
 for the S8 with 225 sg. mm topside heat sinking

$$T_J = (1.03W \times 35^{\circ}C/W) \times + 70^{\circ}C = 106^{\circ}C$$
 for the R package with 100 sq. mm topside heat sinking

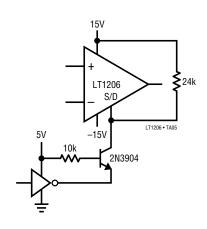
Since the Maximum Junction Temperature is 150°C, the N8 package is clearly unacceptable. Both the S8 and R packages are usable.

## TYPICAL APPLICATIONS

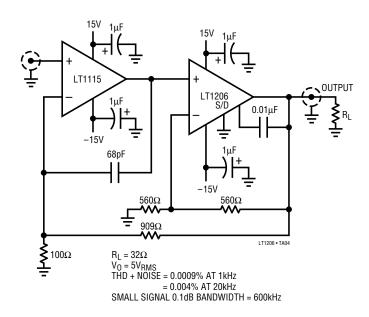
## Precision ×10 Hi Current Amplifier



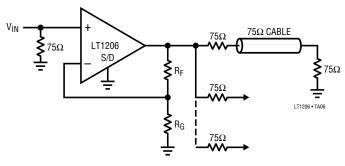
## **CMOS Logic to Shutdown Interface**



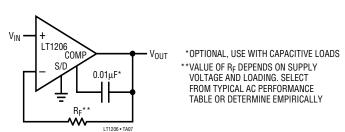
## Low Noise ×10 Buffered Line Driver



### **Distribution Amplifier**



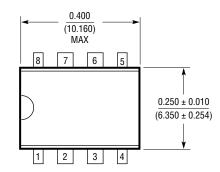
## Buffer $A_V = 1$

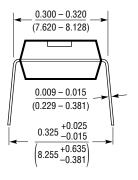


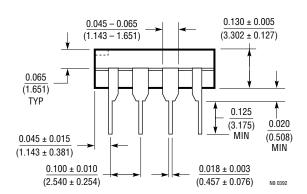


# PACKAGE DESCRIPTION Dimensions in inches (millimeters) unless otherwise noted.

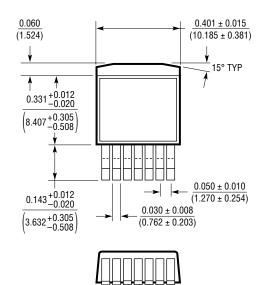
#### N8 Package 8-Lead Plastic DIP

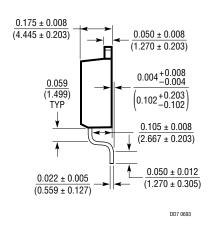






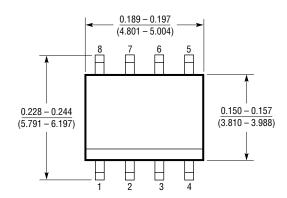
R Package 7-Lead Plastic DD

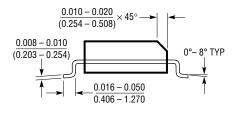


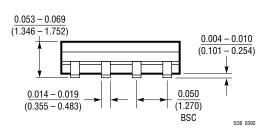


# PACKAGE DESCRIPTION Dimensions in inches (millimeters) unless otherwise noted.

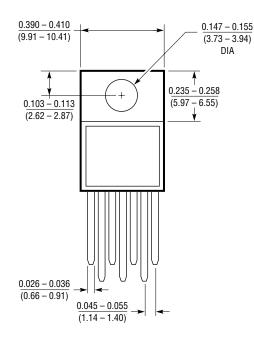
S8 Package 8-Lead Plastic SOIC

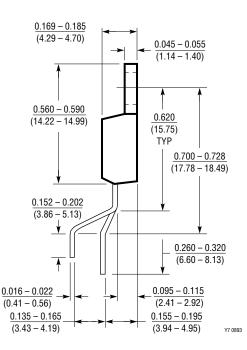






Y Package 7-Lead TO-220





## **NORTHEAST REGION**

**Linear Technology Corporation** One Oxford Valley

2300 E. Lincoln Hwy., Suite 306 Langhorne, PA 19047

Phone: (215) 757-8578 FAX: (215) 757-5631

#### **Linear Technology Corporation**

266 Lowell St., Suite B-8 Wilmington, MA 01887 Phone: (508) 658-3881 FAX: (508) 658-2701

#### **FRANCE**

Linear Technology S.A.R.L.

Immeuble "Le Quartz" 58 Chemin de la Justice 92290 Chatenay Malabry

Phone: 33-1-41079555 FAX: 33-1-46314613

#### **GERMANY**

**Linear Techonolgy GMBH** 

Untere Hauptstr. 9 D-85386 Eching Germany

Phone: 49-89-3197410 FAX: 49-89-3194821

#### **JAPAN**

Linear Technology KK

5F YZ Bldg. 4-4-12 lidabashi, Chiyoda-Ku Tokyo, 102 Japan

Phone: 81-3-3237-7891 FAX: 81-3-3237-8010

#### U.S. Area Sales Offices

#### **SOUTHEAST REGION**

**Linear Technology Corporation** 

17060 Dallas Parkway Suite 208 Dallas, TX 75248

Phone: (214) 733-3071 FAX: (214) 380-5138

#### **CENTRAL REGION**

**Linear Technology Corporation** 

Chesapeake Square 229 Mitchell Court, Suite A-25 Addison, IL 60101

Phone: (708) 620-6910 FAX: (708) 620-6977

## International Sales Offices

#### **KOREA**

Linear Technology Korea Branch

Namsong Building, #505 Itaewon-Dong 260-199 Yongsan-Ku, Seoul

Korea

Phone: 82-2-792-1617 FAX: 82-2-792-1619

#### **SINGAPORE**

Linear Technology Pte. Ltd.

101 Boon Keng Road #02-15 Kallang Ind. Estates

Singapore 1233 Phone: 65-293-5322 FAX: 65-292-0398

## **SOUTHWEST REGION** Linear Technology Corpora-

22141 Ventura Blvd. Suite 206 Woodland Hills, CA 91364

Phone: (818) 703-0835 FAX: (818) 703-0517

#### **NORTHWEST REGION** Linear Technology Corporation

782 Sycamore Dr. Milpitas, CA 95035 Phone: (408) 428-2050 FAX: (408) 432-6331

#### **TAIWAN**

**Linear Technology Corporation** 

Rm. 801, No. 46, Sec. 2 Chung Shan N. Rd. Taipei, Taiwan, R.O.C. Phone: 886-2-521-7575 FAX: 886-2-562-2285

### **UNITED KINGDOM**

Linear Technology (UK) Ltd.

The Coliseum, Riverside Way Camberley, Surrey GU15 3YL

United Kingdom Phone: 44-276-677676 FAX: 44-276-64851

### World Headquarters

**Linear Technology Corporation** 

1630 McCarthy Blvd. Milpitas, CA 95035-7487 Phone: (408) 432-1900 FAX: (408) 434-0507

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