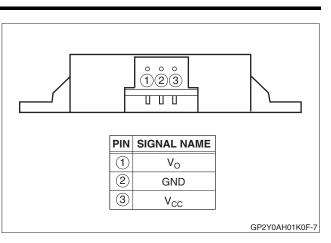


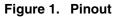
FEATURES

- Analog Output
- LED pulse cycle duration: 32 ms
- Range: 4.5 6.0 mm
- Typical Response time: 39 ms
- Typical Start up delay: 47 ms
- Average current consumption: 20 mA

DESCRIPTION

The GP2Y0AH01K0F is a high-accuracy distance measuring sensor for measuring precise distances in the 4.5 to 6.0 mm range.





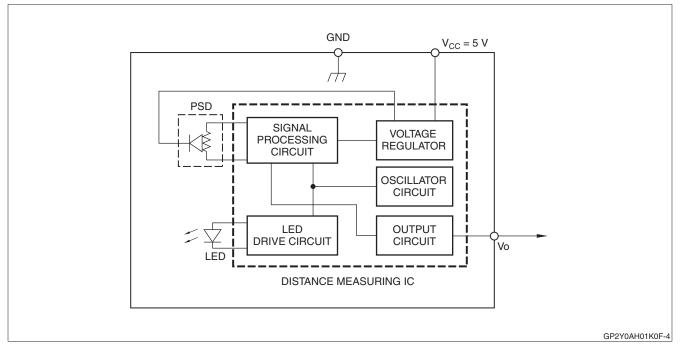


Figure 2. Block Diagram

1

GP2Y0AH01K0F

Optoelectronic Device

ELECTRICAL SPECIFICATIONS

Absolute Maximum Ratings

Ta = 25° C, V_{CC} = 5 VDC

PARAMETER	SYMBOL	RATING	UNIT
Supply Voltage	V _{CC}	-0.3 to +7.0	V
Output Terminal Voltage	Vo	-0.3 to (V _{CC} +0.3)	V
Operating Temperature	Topr	-10 to +60	°C
Storage Temperature	Tstg	-40 to +70	°C

Operating Supply Voltage

PARAMETER	SYMBOL	RATING	UNIT	
Operating Supply Voltage	V _{CC}	4.5 to 5.5	V	

Electro-optical Characteristics

 $Ta = 25^{\circ}C, V_{CC} = 5 VDC$

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNIT	NOTES
Measuring Distance Range	ΔL		4.5	-	6.0	mm	1, 2
Output Terminal Voltage	Vo	L = 6.0 mm	0.35	0.5	0.65	V	1, 2
Output Voltage Difference	ΔV_{O}	Output change at ∆L (4.5 mm - 6.0 mm)	1.56	1.73	1.90	V	1, 2
Average Supply Current	I _{CC}		-	20	40	mA	1, 2

NOTES:

1. Measurements made with Kodak R-27 Gray Card, using the white side, (90% reflectivity).

2. L = Distance to reflective object.

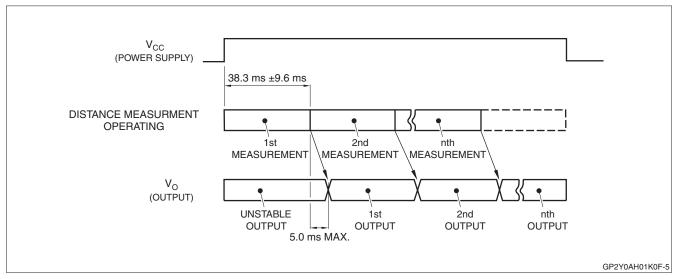


Figure 3. Timing Diagram

REALIABILITY

The reliability of requirements of this device are listed in Table 1.

TEST ITEMS	TEST CONDITIONS	FAILURE JUDGEMENT CRITERIA	SAMPLES (n), DEFECTIVE (C)
Temperature Cycling	One cycle -40°C (30 min.) to +70°C in 30 minutes, repeated 25 times		n = 11, C = 0
High Temperature and High Humidity Storage	+40°C, 90% RH, 500h		n = 11, C = 0
High Temperature Storage	+70°C, 500h		n = 11, C = 0
Low Temperature Storage	-40°C, 500h	Initial $\times 0.8 > \Delta V_{O}$	n = 11, C = 0
Operation Life (High Temperature)	+60°C, V _{CC} = 5 V, 500h	$\Delta V_{O} > Initial \times 1.2$	n = 11, C = 0
Mechanical Shock	100 m/s², 6.0 ms 3 times/±X, ±Y, ±Z direction		n = 8, C = 0
Variable Frequency Vibration	10-to-55-to-10 Hz in 1 minute Amplitude: 1.5 mm 2h in each X, Y, Z direction		n = 8, C = 0

Table 1. Reliability

NOTES:

1. Test conditions are according to Electro-optical Characteristics, shown on page 2.

2. At completion of the test, allow device to remain at nominal room temperature and humidity (non-condensing) for two hours.

3. Confidence level: 90%, Lot Tolerance Percent Defect (LTPD): 20%/40%.

MANUFACTURER'S INSPECTION

Inspection Lot

Inspection shall be carried out per each delivery lot.

Inspection Method

A single sampling plan, normal inspection level II based on ISO 2859 shall be adopted. The AQL for the inspection items is listed in Table 2.

Table 2. Quality Level

DEFECT	INSPECTION ITEM/TEST METHOD	
Major Defect	Electro-optical characteristics defect	0.4
Minor Defect	Defect on appearance and dimension (crack, chip, scratch, stain)*	1.0

NOTE: *Any one of these that affects the Electro-optical Characteristics shall be considered a defect.

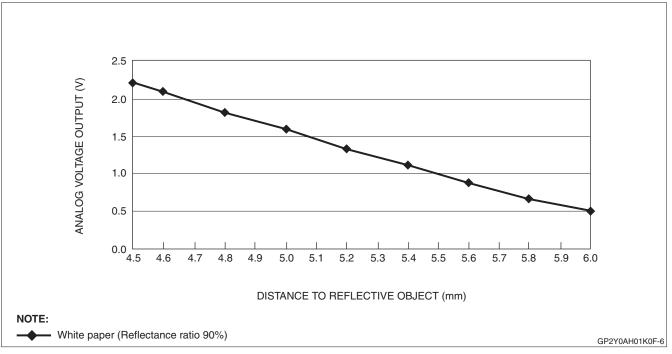
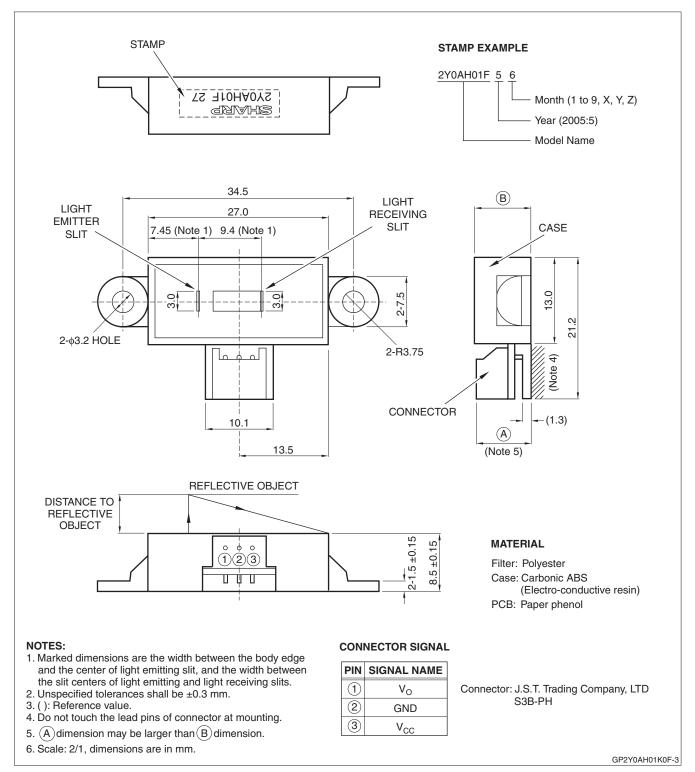
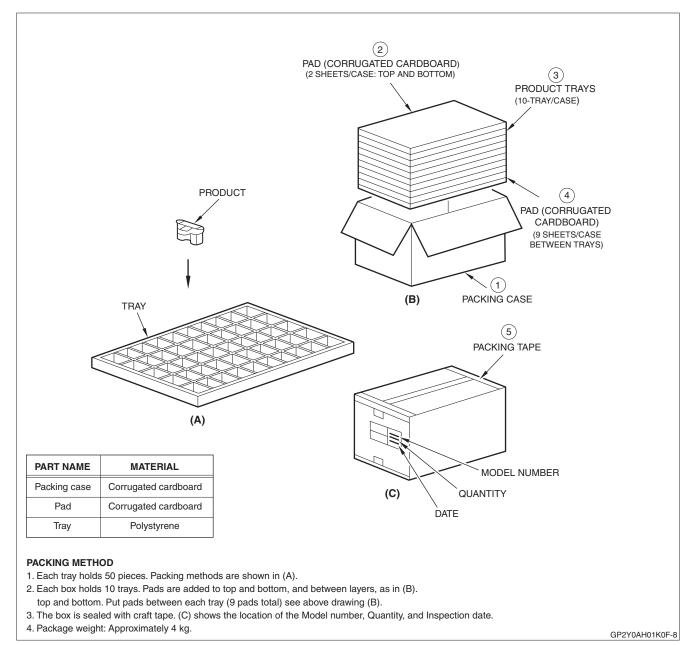


Figure 4. GP2Y0AH01K0F Example of Output Voltage/Distance Characteristics

PACKAGE SPECIFICATIONS



PACKING SPECIFICATION



NOTES

- Keep the sensor lens clean. Dust, water, oil, and other contaminants can deteriorate the characteristics of this device. Applications should be designed to eliminate sources of lens contamination.
- When using a protective cover over the emitter and detector, ensure the cover efficiently transmits light throughout the wavelength range of the LED ($\lambda = 870 \text{ nm} \pm 70 \text{ nm}$). Both sides of the protective cover should be highly polished. Use of a protective cover may decrease the effective distance over which the sensor operates. Ensure that any cover does not negatively affect the operation over the intended application range.
- Objects in proximity to the sensor may cause reflections that can affect the operation of the sensor.
- Sources of high ambient light (the sun or strong artificial light) may affect measurement. For best results, the application should be designed to prevent interference from direct sunlight or artificial light.

- Using the sensor with a mirror can induce measurement errors. Often, changing the incident angle on the mirror can correct this problem.
- If a prominent boundary line exists in the surface being measured, it should be aligned vertically to avoid measurement error. See Figure 6 for further details.
- When measuring the distance to objects in motion, align the sensor so that the motion is in the horizontal direction instead of vertical. Figure 6 illustrates the preferred alignment.
- A 10 μ F (or larger) bypass capacitor between V_{CC} and GND near the sensor is recommended.
- To clean the sensor, use a dry cloth. Use of any liquid to clean the device may result in decreased sensitivity or complete failure.
- Excessive mechanical stress can damage the internal sensor or lens.

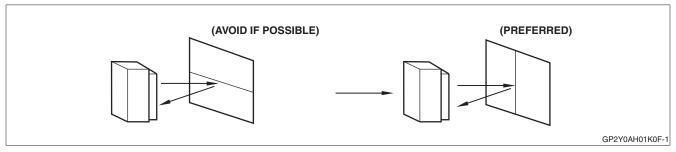


Figure 5. Proper Alignment to Surface Being Measured

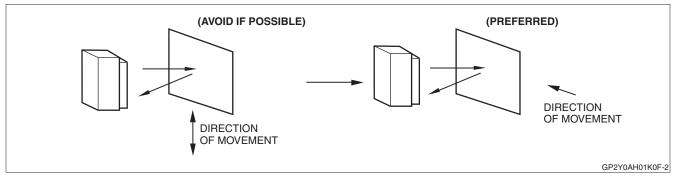


Figure 6. Proper Alignment to Moving Surfaces

SHARP

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