## CLOCK MULTIPLIER WITH DELAY CONTROL AND PHASE ALIGNMENT

## FEATURES

- Low-Jitter Clock Multiplier: $\times 1, \times 2, \times 4, \times 8$
- Programmable Bidirectional Delay Steps of 1.3 mUI
- Output Frequency Range of 25 MHz to 280 MHz
- Input Frequency Range of 12.5 MHz to 240 MHz
- Low Jitter Generation
- Single-Ended REFCLK Input With Adjustable Trigger Level (Works With LVTTL, HSTL, and LVPECL)
- Differential/Single-Ended Output
- Output Can Drive LVPECL, LVDS, and LVTTL
- Three Power Operating Modes to Minimize Power
- Low Power Consumption (< 190 mW at 280 MHz/3.3 V)
- Packaged in a Shrink Small-Outline Package (DBQ)
- No External Components Required for PLL
- Spread Spectrum Clock Tracking Ability to Reduce EMI (SSC)


## APPLICATIONS

- Video Graphics
- Gaming Products
- Datacom
- Telecom
- Noise Cancellation Created by FPGAs



## DESCRIPTION

The CDCF5801 provides clock multiplication from a reference clock (REFCLK) signal with the unique capability to delay or advance the CLKOUT/CLKOUTB with steps of only 1.3 mUl through a phase aligner. For every rising edge on the DLYCTRL pin the CLKOUT is delayed by a $1.3-\mathrm{mUl}$ step size as long as the LEADLAG input detects a low signal at the time of the DLYCTRL rising edge. Similarly for every rising edge on the DLYCTRL pin the CLKOUT is advanced by a $1.3-\mathrm{mUl}$ step size as long as the LEADLAG pin is high during the transition. This unique capability allows the device to phase align (zero delay) between CLKOUT/CLKOUTB and any one other CLK in the system by feeding the clocks that need to be aligned to the DLYCTRL and the LEADLAG pins. Also it provides the capability to program a fixed delay by providing the proper number of edges on the DLYCTRL pin, while strapping the LEADLAG pin to dc high or low. Further possible applications are:

- Aligning the rising edge of the output clock signal to the input clock rising edge
- Avoiding PLL instability in applications that require very long PLL feedback lines
- Isolation of jitter and digital switching noise
- Limitation of jitter in systems with good ppm frequency stability

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The CDCF5801 provides clock multiplication and division from a reference clock (REFCLK) signal. The device is optimized to have extremely low jitter impact from input to output. The predivider pins MULT[0:1] and post-divider pins $\mathrm{P}[0: 2$ ] provide selection for frequency multiplication and division ratios, generating CLKOUT/CLOUTKB frequencies ranging from 25 MHz to 280 MHz with clock input references (REFCLK) ranging from 12.5 MHz to 240 MHz . See Table 11 for detailed frequency support. The selection of pins MULT[0:1] and P[1:2] determines the multiplication value of $1,2,4$, or 8 . The CDCF5801 offers several power-down/ high-impedance modes, selectable by pins PO, STOPB and PWRDN. Another unique capability of the CDCF5801 is the high sensitivity and wide common-mode range of the clock-input pin REFCLK by varying the voltage on the VDDREF pin. The clock signal outputs CLKOUT and CLKOUTB can be used independently to generate single-ended clock signals. The CLKOUT/CLKOUTB outputs can also be combined to generate a differential output signal suitable for LVDS, LVPECL, or HSTL/SSTL signaling. The CDCF5801 is characterized for operation over free-air temperatures of $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$.

FUNCTIONAL BLOCK DIAGRAM


TERMINAL FUNCTIONS

| TERMINAL |  | I/O | DESCRIPTION |
| :--- | :---: | :---: | :--- | :--- |
| NAME | NO. |  |  |
| CLKOUT <br> CLKOUTB | 2018 | O | Output CLK signal (low-noise CMOS) Complementary output CLK signal (low-noise CMOS) |
| DLYCTRL | 7 | I | Every rising edge on this pin delays/advances the CLKOUT/CLKOUTB signal by 1/768th of the <br> CLKOUT/CLKOUTB period (1.3 mUI). (E.g., for a 90-degree delay or advancement one needs to <br> provide 192 rising edges). See [able 3. |
| GND | 5 |  | GND for VDDREF and VDDPD |
| GNDO | 17,21 |  | GND for the output pins (CLKOUT, CLKOUTB) |
| GNDP | 4 |  | GND for the PLL |

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Table 1. Input-to-Output Settings

| INPUT-TO-OUTPUT MULTIPLI-CATION-RATIO | INPUT FREQUENCY (MHz) |  | OUTPUT FREQUENCY (MHz) |  | PREDIVIDER |  | POST DIVIDER |  |  | NOTE |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | FROM | TO | FROM | TO | MULTO | MULT1 | P0 | P1 | P2 |  |
| 8 | 12.5 | 35 | 100 | 280 | 1 | 0 | 0 | 1 | 1 | Normal operation ${ }^{(1)}$ |
| 4 | 12.5 | 39 | 50 | 156 | 1 | 0 |  | 1 | 0 |  |
|  | 25 | 70 | 100 | 280 | 1 | 1 |  | 1 | 1 |  |
| 2 | 12.5 | 39 | 25 | 78 | 1 | 0 |  | 0 | 1 |  |
|  | 25 | 78 | 50 | 156 | 1 | 1 |  | 1 | 0 |  |
|  | 50 | 140 | 100 | 280 | 0 | 0 |  | 1 | 1 |  |
| 1 | 25 | 78 | 25 | 78 | 1 | 1 |  | 0 | 1 |  |
|  | 50 | 156 | 50 | 156 | 0 | 0 |  | 1 | 0 |  |
|  | 100 | 240 | 100 | 240 | 0 | 1 |  | 1 | 1 |  |
| CLKOUT high-impedance |  |  |  |  | X | X | 1 | 0 | 0 | Special mode of operation |
|  |  |  | UOTB high | edance |  |  |  |  |  |  |
|  |  |  |  | = high | X | X |  | 0 | 1 |  |
|  |  |  | CLK | = high |  |  |  |  |  |  |
| CLKOUT = P2 |  |  |  |  | X | X |  | 1 | X |  |
| CLKOUTB = $\overline{\text { P2 }}$ |  |  |  |  |  |  |  |  |  |  |

(1) There is some overlapping of the input frequency ranges for multiplication ratios of 1, 2, and 4 . For example, an input frequency of 30 MHz for a multiplication ratio of four falls within both the 12.5 to $39-\mathrm{MHz}$ range and the 25 to $70-\mathrm{MHz}$ range. For best device operation in a case such as this, always select the input frequency range nearer to the top of the table.

## PLL DIVIDER/MULITPLIER SELECTION

Table 2. Power Down Modes

| STATE | PWRDNB | STOPB | CLKOUT and CLKOUTB |
| :---: | :---: | :---: | :---: |
| Power down | 0 | $X$ | GNDO |
| Clock stop | 1 | 0 | $V_{0}$, STOP |
| Normal | 1 | 1 | See Table 1 |

Table 3. Programmable Delay and Phase Alignment

| DLYCTR | NOTE | LEADLAG | CLKOUT and CLKOUTB |
| :---: | :---: | :---: | :---: |
| Each rising edge + | For every 32 edges, there are one or two edges for which the phase aligner does not update the phase. Therefore, CLKOUT phase is not updated for every $32^{\text {nd }}$ edge. The frequency of the DLYCTRL pin should always be equal to or less than the frequency of the LEADLAG pin. | HI | Advanced by one step: <br> step size: 1/768 of the CLKOUT period ( 1.3 mUI ) at $\mathrm{P}[1: 2]=11$ <br> $1 / 1536$ of the CLKOUT period $(0.65 \mathrm{mUI})$ at $\mathrm{P}[1: 2]=10$ <br> $1 / 3072$ of the CLKOUT period $(0.325 \mathrm{mUI})$ at $\mathrm{P}[1: 2]=01$ |
| Each rising edge + |  | LO | Delayed by one step: <br> step size: $1 / 768$ of the CLKOUT period ( 1.3 mUI ) at $\mathrm{P}[1: 2]=11$ <br> $1 / 1536$ of the CLKOUT period $(0.65 \mathrm{mUI})$ at $\mathrm{P}[1: 2]=10$ <br> $1 / 3072$ of the CLKOUT period $(0.325 \mathrm{mUI})$ at $\mathrm{P}[1: 2]=01$ |

## ABSOLUTE MAXIMUM RATINGS

over operating free-air temperature (unless otherwise noted) ${ }^{(1)}$

| $\mathrm{V}_{\mathrm{DDx}}{ }^{(2)}$ | Supply voltage range | -0.5 V to 4 V |
| :--- | :--- | :--- |
|  | Voltage range at any output terminal | -0.5 V to $\mathrm{V}_{\mathrm{DD}}+0.5 \mathrm{~V}$ |
|  | Voltage range at any input terminal | -0.5 V to $\mathrm{V}_{\mathrm{DD}}+0.5 \mathrm{~V}$ |
| $\mathrm{~T}_{\text {stg }}$ | Storage temperature range | $-65^{\circ} \mathrm{C}$ to $150^{\circ} \mathrm{C}$ |
|  | Lead temperature $1,6 \mathrm{~mm}(1 / 16$ inch) from case for 10 seconds | $260^{\circ} \mathrm{C}$ |

(1) Stresses beyond those listed under, absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under, recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
(2) All voltage values are with respect to the GND terminals.

POWER DISSIPATION RATING TABLE

| PACK- <br> AGE | $\mathbf{T}_{\mathbf{A}} \leq \mathbf{2 5}{ }^{\circ} \mathrm{C}$ POWER <br> RATING | DERATING FAC- <br> TOR $^{(1)}$ ABOVE <br> $=\mathbf{2 5} 5^{\circ} \mathbf{C}$ | $\mathbf{T}_{\mathbf{A}}=85^{\circ} \mathbf{C}$ <br> POWER RATING |
| :---: | :---: | :---: | :---: |
| DBQ | 830 mW | $8.3 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ | 332 mW |

(1) This is the inverse of the junction-to-ambient thermal resistance when board-mounted and with no air flow.

## RECOMMENDED OPERATING CONDITIONS

|  |  | MIN | NOM MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: |
| VDDP, VDDPA, VDDO | Supply voltage | 3 | 3.3 3.6 | V |
| $\mathrm{V}_{\mathrm{IH}}$ (CMOS) | High-level input voltage | 0.7 VDD |  | V |
| $\mathrm{V}_{\text {IL }}$ (CMOS) | Low-level input voltage |  | 0.3 VDD | V |
| $\mathrm{V}_{\mathrm{IL}}$ (DLYCTRL, LEADLAG) | Input signal low voltage |  | $\frac{\text { VDDPD }}{2}-0.2$ | V |
| $\mathrm{V}_{\mathrm{IH}}($ DLYCTRL, LEADLAG) | Input signal high voltage | $\frac{\text { VDDPD }}{2}+0.2$ |  | V |
| (VDDPD) | Input reference voltage for DLYCNTRL and LEADLAG | 1.2 | VDD | V |
| IOH | High-level output current |  | -16 | mA |
| $\mathrm{l}_{\mathrm{OL}}$ | Low-level output current |  | 16 | mA |
| (VDDREF) (see Application section) | Input reference voltage for REFCLK | 1.2 | VDD | V |
| VIL (see Application section) | REFCLK input low voltage |  | $\frac{\text { VDDREF }}{2}-0.2$ | V |
| $\mathrm{V}_{\mathrm{IH}}$ (see Application section) | REFCLK input high voltage | $\frac{\text { VDDREF }}{2}+0.2$ |  | V |
| $\mathrm{T}_{\mathrm{A}}$ | Operating free-air temperature | -40 | 85 | ${ }^{\circ} \mathrm{C}$ |

## TIMING REQUIREMENTS

| PARAMETER |  | MIN | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: |
| $\mathrm{F}_{\text {mod }}$ | Input frequency of modulation, (if driven by SSC CLKIN) |  | 33 | kHz |
|  | Modulation index, nonlinear maximum 0.5\% |  | 0.6\% |  |
| SR | Input slew rate | 1 | 4 | V/ns |
|  | Input duty cycle on REFCLK | 40\% | 60\% |  |
|  | Input frequency on REFCLK | 12.5 | 240 | MHz |
|  | Output frequency on CLKOUT and CLKOUTB | 25 | 280 | MHz |
|  | Allowable frequency on DLYCTRL |  | 240 | MHz |

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TIMING REQUIREMENTS (continued)

| PARAMETER | MIN | MAX |
| :---: | :---: | :---: |
| UNIT |  |  |
| Allowable frequency on LEADLAG | 280 | MHz |
| Allowable duty cycle on DLYCTRL and LEADLAG pins | $25 \%$ |  |

## ELECTRICAL CHARACTERISTICS

over recommended operating conditions (unless otherwise noted)

| PARAMETER |  |  | TEST CONDITIONS ${ }^{(1)}$ |  | MIN | TYP( ${ }^{(2)}$ | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {O(STOP) }}$ | Output voltage during Clkstop mode |  | See Figure 1 |  | 1.1 |  | 2 | V |
| $\mathrm{V}_{\mathrm{O}(\mathrm{X})}$ | Output crossing-point voltage |  | See Figure 1 a | igure 4 | $\frac{\text { VDDO }}{2}-0.2$ |  | $\frac{\text { VDDO }}{2}+0.2$ | V |
| $\mathrm{V}_{\mathrm{O}}$ | Output voltage swing ( $\mathrm{V}_{\mathrm{OH}}-\mathrm{V}_{\mathrm{OL}}$ ) |  | See Figure 1 |  | 1.7 |  | 2.9 | V |
| $\mathrm{V}_{\mathrm{IK}}$ | Input clamp voltage |  | $V_{D D}=3 \mathrm{~V}$, | $\mathrm{I}_{\mathrm{I}}=-18 \mathrm{~mA}$ |  |  | -1.2 | V |
| $\mathrm{V}_{\mathrm{OH}}$ | High-level output voltage |  | $V_{D D}=3$ to 3.6 | See Figure 1 | 2 | 2.5 |  | V |
|  |  |  | $V_{D D}=3 \mathrm{~V}$, | $\mathrm{I}_{\mathrm{OH}}=-16 \mathrm{~mA}$ | 2.2 |  |  |  |
| $\mathrm{V}_{\text {OL }}$ | Low-level output voltage |  | $V_{D D}=3$ to 3.6 | See Figure 1 |  | 0.4 | 0.6 | V |
|  |  |  | $V_{D D}=3 \mathrm{~V}$, | $\mathrm{I}_{\mathrm{OH}}=16 \mathrm{~mA}$ |  |  | 0.5 |  |
| IOH | High-level output current |  | $V_{D D}=3.135 \mathrm{~V}$, | $\mathrm{V}_{\mathrm{O}}=1 \mathrm{~V}$ | -32 | -52 |  | mA |
|  |  |  | $V_{\text {DD }}=3.3 \mathrm{~V}$, | $\mathrm{V}_{\mathrm{O}}=1.65 \mathrm{~V}$ |  | -51 |  |  |
|  |  |  | $\mathrm{V}_{\mathrm{DD}}=3.465 \mathrm{~V}$, | $\mathrm{V}_{\mathrm{O}}=3.135 \mathrm{~V}$ |  | -14.5 | -21 |  |
| ${ }_{\text {IOL }}$ | Low-level output current |  | $\mathrm{V}_{\mathrm{DD}}=3.135 \mathrm{~V}$, | $\mathrm{V}_{\mathrm{O}}=1.95 \mathrm{~V}$ | 43 | 61.5 |  | mA |
|  |  |  | $V_{\text {DD }}=3.3 \mathrm{~V}$, | $\mathrm{V}_{\mathrm{O}}=1.65 \mathrm{~V}$ |  | 65 |  |  |
|  |  |  | $\mathrm{V}_{\mathrm{DD}}=3.465 \mathrm{~V}$, | $\mathrm{V}_{\mathrm{O}}=0.4 \mathrm{~V}$ |  | 25.5 | 40 |  |
| l O | High-impedance-state output current |  | $\mathrm{P} 0=1$, | $\mathrm{P} 1=\mathrm{P} 2=0$ |  |  | $\pm 10$ | $\mu \mathrm{A}$ |
| Ioz(Stop) | High-impedance-state output current during Clk Stop |  | Stop $=0$, | $\mathrm{V}_{\mathrm{O}}=\mathrm{GND}$ or $\mathrm{V}_{\mathrm{DD}}$ |  |  | $\pm 100$ | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\text {OZ(PD) }}$ | High-impedance-state output current in power-down state |  | PWRDNB $=0$, | $\mathrm{V}_{\mathrm{O}}=\mathrm{GND}$ or $\mathrm{V}_{\mathrm{DD}}$ | -10 |  | 100 | $\mu \mathrm{A}$ |
| IIH | High-level input curren | REFCLK; STOPB; PWRDNB; P[0:2]; MULT[0:1]; <br> DLYCTRL; LEADLAG | $\mathrm{V}_{\mathrm{DD}}=3.6 \mathrm{~V}$, | $V_{1}=V_{D D}$ |  |  | 10 | $\mu \mathrm{A}$ |
|  |  |  | $\mathrm{V}_{\mathrm{DD}}=3.6 \mathrm{~V}$, | $V_{1}=0$ |  |  | -10 | $\mu \mathrm{A}$ |
| $\mathrm{Z}_{\mathrm{O}}$ | Output impedance (single ended) | High state | $\mathrm{R}_{\mathrm{I}}$ at $\mathrm{I}_{\mathrm{O}}-14.5 \mathrm{~mA}$ | -16.5 mA | 15 | 35 | 50 | $\Omega$ |
|  |  | Low state | $\mathrm{R}_{1}$ at $\mathrm{I}_{0} 14.5 \mathrm{~mA}$ to 16.5 mA |  | 10 | 17 | 35 |  |
| $\mathrm{I}_{\text {REF }}$ | Reference current | $\mathrm{V}_{\mathrm{DD}}$ REF; VDDPD | $\mathrm{V}_{\mathrm{DD}}=3.6 \mathrm{~V}$ | PWRDNB $=0$ |  |  | 50 | $\mu \mathrm{A}$ |
|  |  |  |  | PWRDNB $=1$ |  |  | 0.5 | mA |
| $\mathrm{C}_{1}$ | Input capacitance |  | $\mathrm{V}_{1}=\mathrm{V}_{\mathrm{DD}}$ or GND |  |  | 2 |  | pF |
| $\mathrm{C}_{0}$ | Output capacitance |  | $\mathrm{V}_{\mathrm{O}}=\mathrm{GND}$ or $\mathrm{V}_{\mathrm{DD}}$ |  |  | 3 |  | pF |
| $\mathrm{I}_{\mathrm{DD}}(\mathrm{PD})$ | Supply current in power-down state |  | $\begin{aligned} & \text { REFCLK }=0 \mathrm{MHz} \text { to } 280 \mathrm{MHz} ; \\ & \text { PWRDNB }=0 ; \text { STOPB }=1 \end{aligned}$ |  |  |  | 4 | mA |
| IDD(CLKSTOP) | Supply current in CLK stop state |  | BUSCLK configured for 280 MHz |  |  |  | 44 | mA |
| IDD(NORMAL) | Supply current (normal operation mode) |  | BUSCLK 280 MHz , MULT[0:1] = 10; P[0:2] = 011; Load, See Figure 1 |  |  |  | 75 | mA |

(1) $V_{D D}$ refers to any of the following; VDDP, VDDREF, VDDO, VDDPD, and VDDPA
(2) All typical values are at $\mathrm{V}_{\mathrm{DD}}=3.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$.

## JITTER SPECIFICATION

over recommended free-air temperature range and $\mathrm{V}_{\mathrm{CC}}$ range (unless otherwise noted)

| PARAMETER |  | TEST CONDITIONS |  |  |  |  | TYP (ps) | MAX (ps) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | REFCLK <br> (MHz) | CLKOUT (MHz) | MULT[0:1] | P[0:2] | NOTES |  |  |
| $\mathrm{t}_{\text {(itter) }}$ | Period rms (1-sigma jitter, full frequency band) | 25 | 25 | 11 | 001 | Phase aligner running (CLKOUT tight to LEADLAG; REFCLK tight to DLYCTRL). All typical values are at VDD $=3.3$ V , $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$. | 20 | 48 |
|  | Period p-p |  |  |  |  |  | 120 | 225 |
|  | Cycle to cycle + |  |  |  |  |  | 70 | 165 |
|  | Cycle to cycle - |  |  |  |  |  | 70 | 165 |
|  | RMS phase jitter (accumulated, $100 \mathrm{kHz}-12.5 \mathrm{MHz}$ ) |  |  |  |  |  | 80 | 160 |
|  | Period rms (1-sigma jitter, full frequency band) | 50 | 50 | 11 | 001 |  | 7 | 15 |
|  | Period p-p |  |  |  |  |  | 37 | 75 |
|  | Cycle to cycle + |  |  |  |  |  | 27 | 55 |
|  | Cycle to cycle - |  |  |  |  |  | 27 | 55 |
|  | RMS phase jitter (accumulated, $100 \mathrm{kHz}-25 \mathrm{MHz}$ ) |  |  |  |  |  | 27 | 65 |
|  | Period rms ( 1 -sigma jitter, full frequency band) | 100 | 100 | 00 | 010 |  | 5 | 14 |
|  | Period p-p |  |  |  |  |  | 30 | 65 |
|  | Cycle to cycle + |  |  |  |  |  | 24 | 55 |
|  | Cycle to cycle - |  |  |  |  |  | 24 | 55 |
|  | RMS phase jitter (accumulated, $100 \mathrm{kHz}-40 \mathrm{MHz}$ ) |  |  |  |  |  | 35 | 65 |
|  | Period rms (1-sigma jitter, full frequency band) | 156 | 156 | 00 | 010 |  | 4 | 8 |
|  | Period p-p |  |  |  |  |  | 20 | 40 |
|  | Cycle to cycle + |  |  |  |  |  | 17 | 40 |
|  | Cycle to cycle - |  |  |  |  |  | 17 | 40 |
|  | RMS phase jitter (accumulated, $100 \mathrm{kHz}-40 \mathrm{MHz}$ ) |  |  |  |  |  | 15 | 35 |
|  | Period rms (1-sigma jitter, full frequency band) | 200 | 200 | 01 | 011 |  | 8 | 15 |
|  | Period p-p |  |  |  |  |  | 38 | 60 |
|  | Cycle to cycle + |  |  |  |  |  | 5 | 55 |
|  | Cycle to cycle - |  |  |  |  |  | 35 | 55 |
|  | RMS phase jitter (accumulated, $100 \mathrm{kHz}-40 \mathrm{MHz}$ ) |  |  |  |  |  | 30 | 60 |

CDCF5801

## JITTER SPECIFICATION (continued)

over recommended free-air temperature range and $\mathrm{V}_{\mathrm{CC}}$ range (unless otherwise noted)

| PARAMETER |  | TEST CONDITIONS |  |  |  |  | TYP (ps) | MAX (ps) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | REFCLK (MHz) | CLKOUT (MHz) | MULT[0:1] | $\mathrm{P}[0: 2]$ | NOTES |  |  |
| $\mathrm{t}_{\text {(jitter) }}$ | Period rms (1-sigma jitter, full frequency band) | 25 | 200 | 10 | 011 | Phase aligner not running <br> (LEADLAG $=0$, <br> DLYCTRL = <br> 0). All typical values are at <br> $\mathrm{VDD}=3.3$ <br> $\mathrm{V}, \mathrm{T}_{\mathrm{A}}=$ <br> $25^{\circ} \mathrm{C}$. | 4 | 11 |
|  | Period p-p |  |  |  |  |  | 20 | 48 |
|  | Cycle to cycle + |  |  |  |  |  | 16 | 45 |
|  | Cycle to cycle - |  |  |  |  |  | 16 | 45 |
|  | Period rms (1-sigma jitter, full frequency band) | 25 | 100 | 10 | 010 |  | 4 | 11 |
|  | Period p-p |  |  |  |  |  | 22 | 55 |
|  | Cycle to cycle + |  |  |  |  |  | 15 | 45 |
|  | Cycle to cycle - |  |  |  |  |  | 15 | 45 |
|  | Period rms (1-sigma jitter, full frequency band) | 70 | 280 | 11 | 011 |  | 4 | 11 |
|  | Period p-p |  |  |  |  |  | 18 | 48 |
|  | Cycle to cycle + |  |  |  |  |  | 15 | 45 |
|  | Cycle to cycle - |  |  |  |  |  | 15 | 45 |
|  | Period rms ( 1 -sigma jitter, full frequency band) | 25 | 50 | 10 | 001 |  | 6 | 16 |
|  | Period p-p |  |  |  |  |  | 34 | 75 |
|  | Cycle to cycle + |  |  |  |  |  | 20 | 65 |
|  | Cycle to cycle - |  |  |  |  |  | 20 | 65 |
|  | Period rms (1-sigma jitter, full frequency band) | 78 | 156 | 11 | 010 |  | 3 | 11 |
|  | Period p-p |  |  |  |  |  | 15 | 44 |
|  | Cycle to cycle + |  |  |  |  |  | 13 | 40 |
|  | Cycle to cycle - |  |  |  |  |  | 13 | 40 |
|  | Period rms (1-sigma jitter, full frequency band) | 62.5 | 125 | 00 | 011 |  | 6 | 20 |
|  | Period p-p |  |  |  |  |  | 35 | 80 |
|  | Cycle to cycle + |  |  |  |  |  | 25 | 75 |
|  | Cycle to cycle - |  |  |  |  |  | 25 | 75 |

## SWITCHING CHARACTERISTICS

over recommended operating free-air temperature range (unless otherwise noted)

| PARAMETER |  | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{t}_{\text {(DC) }}$ | Output duty cycle over 1000 cycles | See Figure 3 | 42\% |  | 58\% |  |
| $\mathrm{tr}_{\mathrm{r}}, \mathrm{t}_{\mathrm{f}}$ | Output rise and fall times (measured at 20\%-80\% of output voltage | See Figure 5 | 150 | 250 | 350 | ps |

## STATE TRANSITION LATENCY SPECIFICATIONS

|  | PARAMETER | FROM | TO | TEST CONDITION | MIN | TYP MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{t}_{\text {(powerup) }}$ | Delay time, PWRDNB $\uparrow$ to CLKOUT / CLKOUTB settled | Power down | Normal | See Figure 6 |  | 3 | ms |
|  | Delay time, PWRDNB $\uparrow$ to internal PLL and clock are on and settled |  |  |  |  | 3 |  |

## STATE TRANSITION LATENCY SPECIFICATIONS (continued)

| PARAMETER |  | FROM | TO | TEST CONDITION | MIN | TYP MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{t}_{\text {(VDDpowerup) }}$ | Delay time, power up to CLKOUT output settled | $V_{D D}$ | Normal | See Figure 6 |  | 3 | ms |
|  | Delay time, power up to internal PLL and clock are on and settled |  |  |  |  | 3 |  |
| $\mathrm{t}_{\text {(MULT }}$ | MULTO and MULT1 change to CLKOUT output resettled | Normal | Normal | See Figure 7 |  | 1 | ms |
| $\mathrm{t}_{\text {(CLKON })}$ | STOPB $\uparrow$ to CLKOUT glitch-free clock edges | CLK stop | Normal | See Figure 8 |  | 10 | ns |
| $\mathrm{t}_{\text {(CLKSETL) }}$ | STOPB $\uparrow$ to CLKOUT output settled to within 50 ps of the phase before STOPB was disabled | CLK stop | Normal | See Figure 8 |  | 20 | cycles |
| $\mathrm{t}_{\text {(CLKOFF) }}$ | STOPB $\downarrow$ to CLKOUT output disabled | Normal | CLK stop | See Figure 8 |  | 5 | ns |
| $t_{\text {(powerdown) }}$ | Delay time, PWRDNB $\downarrow$ to the device in the power-down mode | Normal | Power down | See Figure 6 |  | 1 | ms |
| $\mathrm{t}_{\text {(STOP) }}$ | Maximum time in CLKSTOP (STOPB = 0 ) before reentering normal mode (STOPB = 1) | STOPB | Normal | See Figure 8 | 100 |  | $\mu \mathrm{s}$ |
| $\mathrm{t}_{(\mathrm{ON})}$ | Minimum time in normal mode (STOPB $=1$ ) before reentering CLKSTOP $(\mathrm{STOPB}=0)$ | Normal | CLK stop | See Figure 8 | 100 |  | ms |

PARAMETER MEASUREMENT INFORMATION

## TESTING CONDITIONS



Figure 1. Test Load and Voltage Definitions $\mathrm{V}_{\mathrm{OH}}, \mathrm{V}_{\mathrm{OL}}, \mathrm{V}_{\mathrm{O}(\mathrm{STOP})}$


Cycle-to-Cycle Jitter $\left(\mathbf{t}_{\text {(jitter }}\right)=\left|\mathrm{t}_{\text {CYCLE }}(\mathbf{i})-\mathrm{t}_{\text {CYCLE }}(\mathbf{i}+1)\right|$ over 1000 consecutive cycles
Figure 2. Cycle-to-Cycle Jitter

## PARAMETER MEASUREMENT INFORMATION (continued)



Duty Cycle $=\left(\mathbf{t p W}_{+} / \mathbf{t}_{\text {CYCLE }}\right)$
Figure 3. Output Duty Cycle


Figure 4. Crossing Point Voltage


Figure 5. Voltage Waveforms


Figure 6. PWRDNB Transition Timings


Figure 7. MULT Transition Timings

## PARAMETER MEASUREMENT INFORMATION (continued)


A. $\quad V_{\text {ref }}=V_{O} \pm 200 \mathrm{mV}$

Figure 8. STOPB Transition Timings

## APPLICATION INFORMATION

## APPLICATION EXAMPLE

The following figure shows an example of using the CDCF5801 as a phase aligner de-skewing the unknown buffer delay of the two CDCV304s in the circuit. This circuitry would not be possible with a simple PLL because the feedback of the PLL would have the second CDCV304 in the loop, causing instability of the PLL due to a long delay.


Figure 9. Application Example
NOTE:
If an active element (microcontroller, ASIC, DSP < FPYA, DSP, etc.) is used in the CDCF5801 CLKOUT to DLYCTRL feedback loop, see application report SCAA075.

## SELECTING VDDREF

Generally, VDDREF can be set to any value between 1.2 V and VDD. The setting of VDDREF directly influences the trigger voltage of the input. Special care must be taken when using small signal swings to drive the CVDCF5801 input (e.g., PECL). It is recommended to connect VDDREF directly to VDD, ac-couple the REFCLK input, and rebias the signal.
The following circuit is recommended to drive the CDCF5801 from a differential clock signal like PECL.

## APPLICATION INFORMATION (continued)


A. NOTE: If more signal swing is required and an unterminated transmission is on option, then R1 and R2 can both be replaced with $10-\mathrm{k} \Omega$ resistors.

CDCF5801
INSTRUMENTS

Revision History

| DATE | REV | PAGE | SECTION |  |
| :---: | :---: | :---: | :---: | :--- |
| 29 JUL 05 | E | 13 | Application Example | Changed first paragraph and changed P2 connection in Figure 9 |
| 18 DEC <br> 04 | D | - | - | Unknown |
| 17 FEB 04 | C | - | - | Unknown |
| 15 OCT <br> 03 | B | - | - | Unknown |
| 9 OCT 03 | A | - | - | Unknown |
| 16 SEP 03 | $*$ | - | - | Original version |

## PACKAGING INFORMATION

| Orderable Device | Status $^{(1)}$ | Package <br> Type | Package <br> Drawing | Pins Package <br> Qty |  |  | Eco Plan ${ }^{(2)}$ | Lead/Ball Finish | MSL Peak Temp ${ }^{(3)}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CDCF5801DBQ | ACTIVE | SSOP/ <br> QSOP | DBQ | 24 | 50 |  <br> no Sb/Br) | CU NIPDAU | Level-2-260C-1 YEAR |  |
| CDCF5801DBQR | ACTIVE | SSOP/ <br> QSOP | DBQ | 24 | 2500 |  <br> no Sb/Br) | CU NIPDAU | Level-2-260C-1 YEAR |  |
| CDCF5801DBQRG4 | ACTIVE | SSOP/ <br> QSOP | DBQ | 24 | 2500 |  <br> no Sb/Br) | CU NIPDAU | Level-2-260C-1 YEAR |  |

${ }^{(1)}$ The marketing status values are defined as follows:
ACTIVE: Product device recommended for new designs.
LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
NRND: Not recommended for new designs. Device is in production to support existing customers, but Tl does not recommend using this part in a new design.
PREVIEW: Device has been announced but is not in production. Samples may or may not be available.
OBSOLETE: TI has discontinued the production of the device.
${ }^{(2)}$ Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS) or Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.
TBD: The Pb -Free/Green conversion plan has not been defined.
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${ }^{(3)}$ MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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DBQ (R-PDSO-G24)

## PLASTIC SMALL-OUTLINE PACKAGE



NOTES: A. All linear dimensions are in inches (millimeters).
B. This drawing is subject to change without notice.
C. Body dimensions do not include mold flash or protrusion not to exceed $0.006(0,15)$ per side.
D. Falls within JEDEC MO-137 variation AE.

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